



## ***EC Motors with LinMot Drives***

**Documentation of how to control EC Motors with  
LinMot Drives**



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**EC Motors with  
B1100 / C1100 / C1200 / E1100 / E1200  
Series Drives**

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Note

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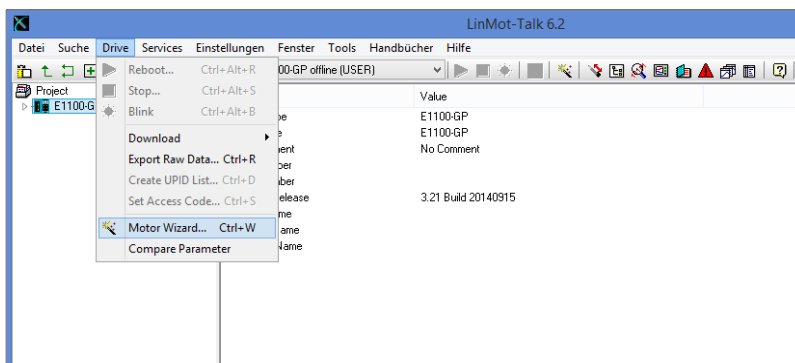
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## 1 Introduction

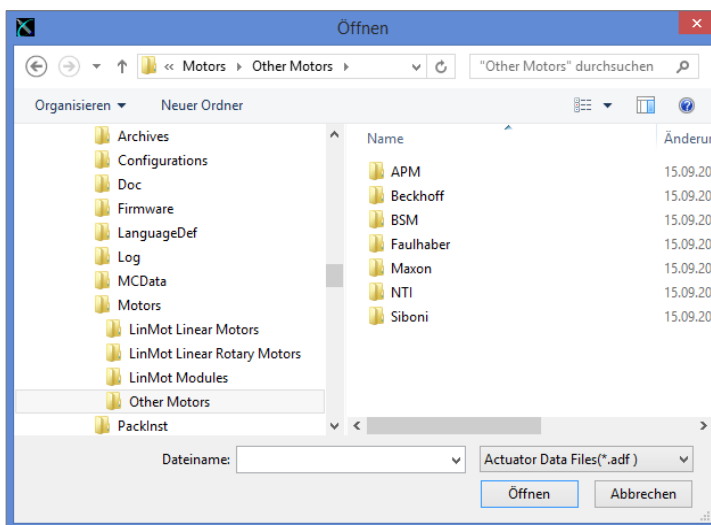
3 phases rotary EC motors control support	
Drives series	Supported since firmware release
E1100	3.4
B1100	3.7
E1200	3.11, 5.0, 6.0
C1100, C1200	6.0

## 2 Configuration

The rotary EC motors are configured by using the LinMot-Talk software. For a couple of motor types LinMot provides actuator definition files (\*.adf). With such an ADF-file the motor configuration can be done by using the *Motor Wizard* tool of the LinMot-Talk software.



You will find the EC motor ADF-files in the subdirectory \Motors\Other Motors\ of your LinMot-Talk installation.



After selecting an EC motor ADF-file, the *Motor Wizard* will guide through the configuration step by step.

### 3 Motors with ADF-File

#### 3.1 NTI Servo Motors

Supported Types:	EC01-40/100
Feedback:	Hall switches & ABZ encoder
Commutation:	<ul style="list-style-type: none"> <li>- Based on hall switches until first Z pulse from encoder</li> <li>- Based on encoder signals afterwards (sine commutation)</li> </ul>
Position Control:	- Based on feedback from ABZ encoder

Wiring:

	B1100	C1100 C1200	E1100	E1200
Motor Phases U,V,W and Ground	X2 or X3	X2	X2 or X3	X2
Hall Switches U, V, W	X13	X13	X10  U → A V → B W → Z	X13
RS422 ABZ Encoder Signals	X13	X13	X12	X13
Sensor supply (5V) from	X13	X13	X12	X13

See also chapter 4 "Sensor and differential Hall Switches Wiring".

#### 3.2 APM Servo Motors (e.g. from Elmo Motion Control)

Supported Types:	APM SA01ACx-9 APM SB02ADx-9 APM SB03ADx-9
Feedback:	Hall switches & ABZ encoder
Commutation:	<ul style="list-style-type: none"> <li>- Based on hall switches until first Z pulse from encoder</li> <li>- Based on encoder signals afterwards (sine commutation)</li> </ul>
Position Control:	- Based on feedback from ABZ encoder

Wiring:

	B1100	C1100 C1200	E1100	E1200
Motor Phases U,V,W and Ground	X2 or X3	X2	X2 or X3	X2
Hall Switches U, V, W	X13	X13	X10  U → A V → B W → Z	X13
RS422 ABZ Encoder Signals	X13	X13	X12	X13
Sensor supply (5V) from	X13	X13	X12	X13

See also chapter 4 "Sensor and differential Hall Switches Wiring".

### 3.3 Berger Lahr RECM

Supported Types: RECM 372/4 DC048 xl  
 RECM 374/4 DC048 xl  
 RECM 375/4 DC060 xl  
 RECM 377/4 DC060 xl

Feedback: Hall switches & ABZ encoder

Commutation: - Based on hall switches until first Z pulse from encoder  
 - Based on encoder signals afterwards (sine commutation)

Position Control: - Based on feedback from ABZ encoder

Wiring:

	B1100	C1100 C1200	E1100	E1200
Motor Phases U,V,W and PE Earth	X2 or X3	X2	X2 or X3	X2
Hall Switches U, V, W	X13	X13	X10  U → A V → B W → Z	X13
RS422 ABZ Encoder Signals	X13	X13	X12	X13
Sensor supply (5V) from	X13	X13	X12	X13

See also chapter 4 "Sensor and differential Hall Switches Wiring".

### 3.4 *Faulhaber EC Motors*

Supported Types:

- 1628 T 024 B K1155
- 2036 U 024 B K1155
- 2036 U 036 B K1155
- 2444 S 024 B K1155
- 2444 S 048 B K1155
- 3056 K 024 B K1155
- 3056 K 036 B K1155
- 3242 G 024 BX4 3692
- 3268 G 024 BX4 3692
- 3274 G 024 BP4 3692
- 3564 K 024 B K1155
- 3564 K 036 B K1155
- 3564 K 048 B K1155
- 4490 H 024 B K1155
- 4490 H 048 B K1155

3268 G 024 BX4 IE3 – 1024 L

LM 1247 – 020 - 01  
LM 1247 – 080 - 01  
LM 1247 – 120 - 01

LM 2070 – 040 - 01  
LM 2070 – 080 - 01  
LM 2070 – 120 - 01

Feedback: Analog hall sensors & optional encoder

Commutation: - Based on hall sensor signals

Position Control: - Based on hall sensor signals or optional encoder

Wiring:

	B1100	C1100 C1200	E1100	E1200
Motor Phases A,B,C A → U B → V C → W	X2 or X3	X2	X2 or X3	X2
Hall Sensors A,B,C A → X3.4 B → X3.9 C → do not connect!	X3	X3	X3	X3
Optional Encoder	X13	X13	X12	X13

### 3.5 Siboni Motors

Supported Types:	B60L 585 B60C 596 S0402B 454
Feedback:	Hall Switches & ABZ Encoder
Commutation:	- Based on hall switches until first Z pulse from encoder - Based on encoder signals afterwards (sine commutation)
Position Control:	- Based on feedback from ABZ encoder
Thermal protection:	- PTC

#### Wiring:

	B1100	C1100 C1200	E1100	E1200
Motor Phases U, V, W and Earth U → W V → V W → U	X2 or X3	X2	X2 or X3	X2
Hall Switches U, V, W	X13	X13	X10  U → A V → B W → Z	X13
RS422 ABZ Encoder Signals Supply +5V red GND black SHIELD SHIELD CH A blue CH /A blue/black CH B green CH /B green/black CH Z yellow CH /Z yellow/black Hall U brown Hall /U brown/black Hall V grey Hall /V grey/black Hall W white Hall /W white/black	X13	X13	X12	X13
Sensor supply (5V) from	X13	X13	X12	X13
PTC			X4.10/X4.11	X4.10/X4.11

See also chapter 4 "Sensor and differential Hall Switches Wiring".

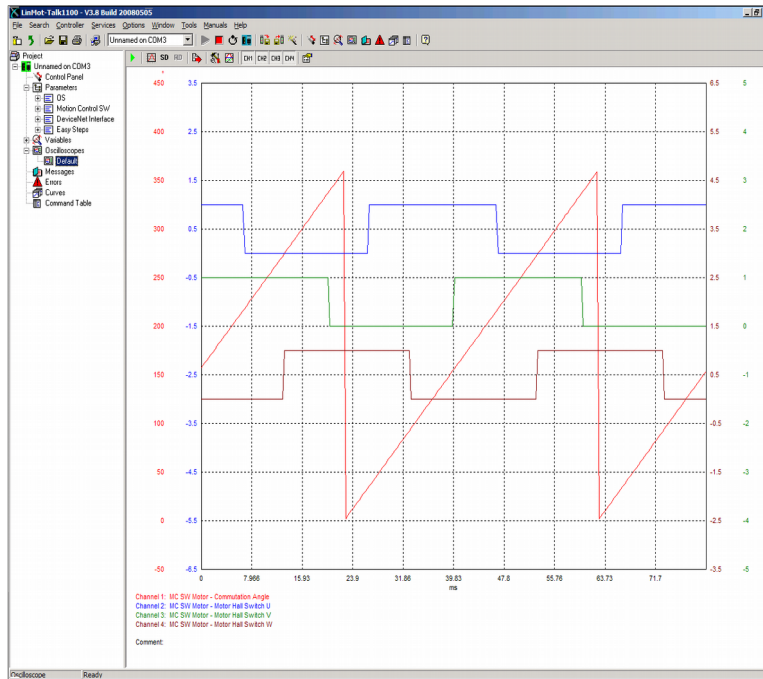


## 4 Sensor and differential Hall Switches Wiring

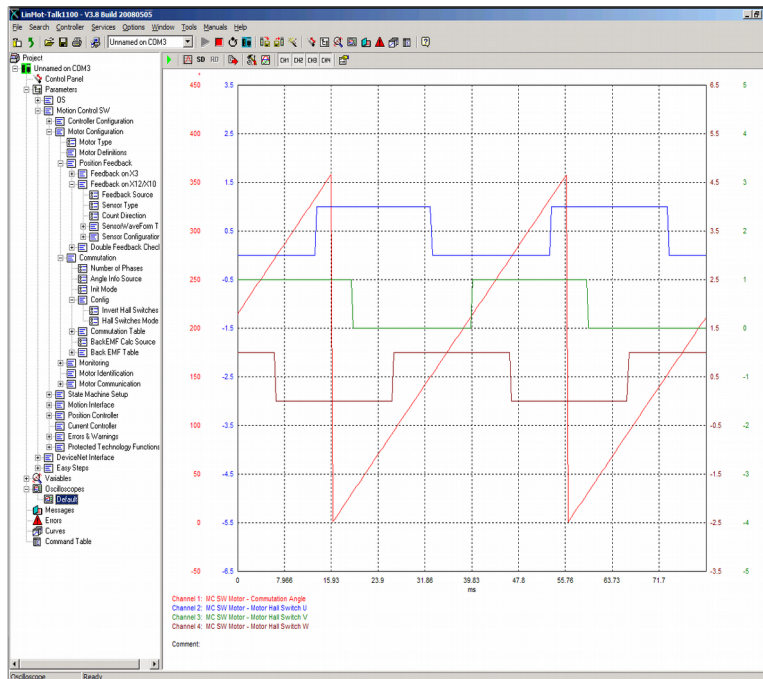
Signal	B1100, C1100, C1200 & E1200	E1100	
		X12 - Pin	X10 - Pin
	X13 - Pin		
+5V	1	1	
/A	2	2	
/B	3	3	
/Z	4	4	
GND	5	5	
/U	6		2
/V	7		6
/W	8		5
A	9	6	
B	10	7	
Z	11	8	
Enc. Alarm	12	9	
U	13		1
V	14		3
W	15		4
Shield	case	case	case

Figure 1: B1100, C1100, C1200, E1100 and E1200 sensor and differential hall switches wiring

## 5 Hall Switches vs. Commutation Angle



**Figure 2: Hall switches vs. commutation angle situation 1 (Hall Switches Mode = Left Aligned)**



**Figure 3: Hall switches vs. commutation angle situation 2 with changed direction (Hall Switches Mode = Left Aligned)**

## 6 Contact Addresses

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