

SERVO DRIVE F1150-DS-UC-3S



- Compact Drive with EtherCAT and CANopen interface
- Optimized for LinMot motors and third party actuators
- Configuration over Ethernet (X15) or EtherCAT (EoE)
- 32A power stage with STO safety
- Interface for incremental & absolute encoders
- Plug and Play (PnP) motor configuration



Servo Drive F1150-DS-UC-3S

F1150 servo drives are axis controllers with 32-bit position resolution and integrated power stage for linear motors and rotary motors. The controllers are suitable for standard and high-end positioning tasks with NC synchronisation.

This flexible hardware in a compact design enables control of any 2/3 phase motor. This means that low power rotary servomotors such as brushless DC motors can also be integrated into the same control concept. The LinMot F1150 servo drives offer a universal solution for a flexible drive concept in single and multi-axis applications with linear motors and other actuators.

The drives have two separate power supplies for the logic and power sections. This has the advantage that the drive and linear motor do not need to be re-initialised when machine power is restored, as all process data, including the actual position of the linear motor, is still up to date.

The ultra-fast control cycle, combined with the high resolution of the A/D converter, ensures perfect motor control for demanding positioning tasks. Features include interpolated motion, trajectory tracking, motion profile positioning and position streaming. The drives can be configured directly from the higher-level control system. The Ethernet interface ensures fast parameter transfer. The F1150 Servo Drive with 3S Safety allows the drives to be stopped safely using control signals (STO) without undercutting the power stage.

Freely programmable analogue and digital inputs and fast trigger inputs are available as fast process interfaces or for direct evaluation of sensor signals.

Easy configuration is guaranteed by the intuitive LinMot Talk PC software. In addition to online documentation, comprehensive debugging tools such as an oscilloscope or error memory ensure fast commissioning of the axes. Plug-and-play motors are automatically detected and configured.

The F1150 servo drives offer all the necessary interfaces to equip linear motors or rotary motors with optional peripherals such as reference and limit switches or high-precision external position sensors.





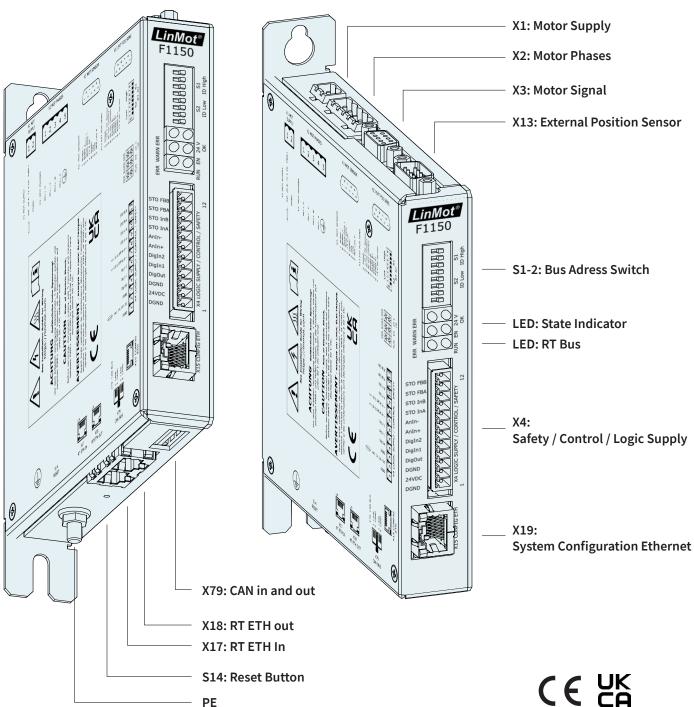
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|---|---|
| Power Supply | 72 VDC (24 L- 05 VDC) |
| | 72 VDC (24 to 85 VDC) |
| Maximum Supported Motor Current | |
| | 32 A _{pk} (0 to 599 Hz) |
| Logic Supply | |
| | 24 VDC (22 to 26 VDC) |
| Control | |
| LinMot Motors P0x / PR0x | • |
| Selected third party motors (contact support) | • |
| Plug and Play (PnP) Auto Configuration | • |
| Phase short-circuit on STO, disable- and error-states* | • |
| Technology Functions | |
| | Point-to-Point Entries (VAI) |
| | Limited Jerk Motion Commands (VAIJ) |
| | Process Monitoring |
| | Command Table with up to 255 Entries |
| | Plug and Play (PnP) Auto Configuration |
| | Time Curves up to 50 Motion Profiles / Up to 8110 Curve Points |
| | Real Time Streaming |
| | Drive Profiles |
| Fieldbuses (Protocols) | |
| EtherCAT CiA402 (preinstalled) | • |
| CANopen up to 1MBaud (CANopen FW must be installed) | (•) |
| Interfaces | |
| Analog Inputs +-10V | 1 |
| Digital Inputs / Outputs 24 V | 2/1 |
| Brake Output 24 V / 0.8 A | 1 |
| Incremental (RS422 up to 25 Mcounts/s, A-B only, Z not supp.) | |
| Absolute (SSI, BiSS-B, BiSS-C, EnDat2.1, EnDat 2.2) | |
| Configuration Interface | |
| Ethernet (X15), 100BASE-TX, IPV4 and IPV6 | |
| Ethernet (EoE) (only if EtherCAT is used) | |
| Timings | |
| Min. Bus Cycle Time | 500 μs |
| PWM Frequency | 16 kHz |
| Trigger Commands | ≥ 250 µs |
| Position Drive | 250 µs |
| Integrated Safety Functions | 200 μ0 |
| Safe Torque Off (STO) with phase short-circuit (3S-Safety) | |
| Certification | |
| cULus - pending | The F1150-DS-UC-3S-xxx will be listed according UL61800-5-1 (pending, this is planned to be done until the end of the year 2025). |

^{*} This feature greatly improves the system behavior on the STO and error states, because the motor will be braked by the eddy current.





CANopen

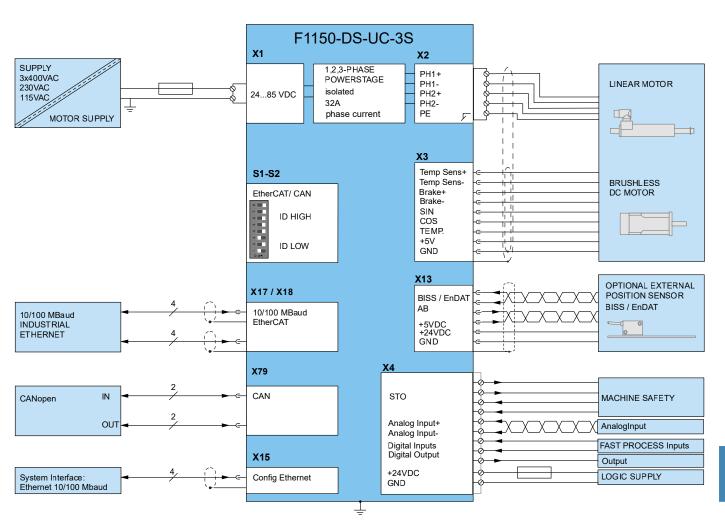


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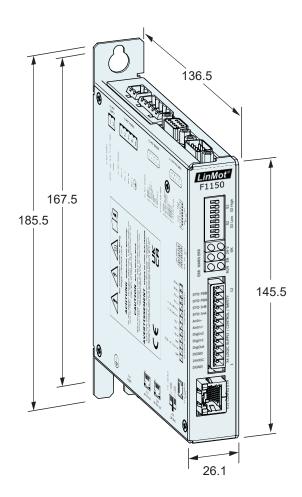
cULus - pending

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Dimensions in mm Mouting points for M5 screws

| Servo Drive | | F1150-DS-UC-3S | |
|---------------------------------------|----------------|---|--|
| Width | mm (in) | 26.1 (1.03) | |
| Height | mm (in) | 145.5 (5.73) | |
| Height with fixings | mm (in) | 185.5 (7.30) | |
| Depth | mm (in) | 136.5 (5.37) | |
| Weight | g (lb) | 765 (1.67) | |
| Mounting Screws | | 2 x M5 | |
| Mounting Distance between screw holes | mm (in) | 167.5 (6.59) | |
| Case IP Code | IP | 20 | |
| Storage temperature | °C | -2540, maximum change 20 K/hour | |
| Transport temperature | °C | -2070 | |
| Operating temperature | °C | 540 at rated data | |
| Relative humidity | | < 85 % (non-condensing) | |
| Air pressure | hPa | 7001060 | |
| Exposure to ionizing radiation | | Not acceptable | |
| Exposure to corrosive environment | | Not acceptable | |
| EMC | | EN/IEC 61000-6-7 (Functional Safety) | |
| Pollution | IEC/EN 60664-1 | Pollution degree 2 | |
| Shock resistance (30 ms) | g (lb) | 5 (0.01) | |
| Vibration resistance (10-150 Hz) | g (lb) | 1 (0.002) | |
| Max. case temperature | °C | 70 | |
| Max. power dissipation | W | 30 | |
| Mounting place | | in the control cabinet (minimum IP54) | |
| Mounting position | | vertical | |
| Distance between Drives | mm (in) | Without power derating *: 20 (0.8) horizontal / 50 (2) vertical With power derating *: 5 (0.2) horizontal / 20 (0.8) vertical | |

^{*} The derating is depending on the situation in the cabinet. The temperature of the drive should be checked under full load (the temperature should be stable, which may take an hour or more). This allows to verify that enough margin is there if the cabinet goes to the maximum allowable temperature of 40° C. For example, if the drive temperature reaches 45° C and the cabinet temperature is 30° C, this would result in a drive temperature of about 55° C at a cabinet temperature of 40° C. The warning level of the drive is configured by default to 75° C and the error level to 80° C. In this example, everything is fine. If the drive temperature is long time above the warning level, this might result in a reduced lifetime of the drive.



| Servo Drives | | | | |
|--------------------|-------------------------|------------------|--|--|
| Item | Description | Part Number | | |
| F1150-DS-UC-3S-000 | DS Drive (72V/32A), STO | <u>0150-6489</u> | | |

| Accessories | | | | | |
|---------------------------|--|------------------|--|--|--|
| Item | Description | Part Number | | | |
| Single Connector | All included in set 0150-4391 | | | | |
| DC01-C1X00/X2 | Drive Connector Motor Phases | <u>0150-3526</u> | | | |
| Compatible Power Supplies | | | | | |
| S02-72/600 | Power Supply 72V/600W (1500W Peak), 120-230VAC | <u>0150-5700</u> | | | |
| S02-72/1000 | Power Supply 72 V/1000 W, 3x400-480 VAC | <u>0150-4535</u> | | | |
| S01-24/500 | Power Supply 24 V/500 W, 1x120/230 VAC | <u>0150-2480</u> | | | |



The connectors X1 and X4 are delivered together with the drive! The connector X2 is included on the motor cable.



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