

Installation Guide Linear Motors

ENG

P10-70-SSC / P10-70-SSC-Dxx



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1 General information

1.1 Introduction

This manual includes instructions for the assembly, installation, maintenance, transport, and storage of linear motors. The document is intended for electricians, mechanics, service technicians, and warehouse staff. Be sure to observe the general safety instructions as well as those in each chapter at all times. Keep this manual accessible to the assigned staff.

1.2 Explanation of symbols



Triangular warning symbols warn against a danger.



Round command symbols tell what to do.

1.3 Qualified personnel

All work such as transport, installation, commissioning and service is only allowed to be carried out by qualified personnel. Qualified personnel in the sense of the safety instructions in this documentation are persons who are familiar with the transport, installation, assembly, commissioning and operation of the product and who have the appropriate qualifications.

This manual must be read carefully before transport, installation, commissioning, service and all safety-related information must be adhered to.

1.4 Liability

NTI AG (as manufacturer of LinMot linear motors and MagSpring products) excludes all liability for damages and expenses caused by incorrect use of the products. This also applies to false applications, which are caused by NTI AG's own data and notes, for example in the course of sales, support or application activities. It is the sole responsibility of the user to check the information and information provided by NTI AG regarding their safety-relevant correctness. In addition, the entire responsibility for safety-related product functionality lies exclusively with the user. Product warranties are void if products are used with stators, sliders, servo drives or cables not manufactured by NTI AG unless such use was specifically approved by NTI AG. NTI AG's warranty is limited to repair or replacement as stated in our standard warranty policy as described in our "terms and conditions" previously supplied to the purchaser of our equipment (please request copy of same if not otherwise available). Further reference is made to our general terms and conditions.

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2 Safety instructions



Contusions

Sliders contain neodymium magnets and have a strong attractive force. Careless handling could cause fingers or skin to become pinched between two sliders. This may lead to contusions, bruises, and bone fractures.

When handling sliders, wear thick protective gloves and keep a minimum distance between sliders. Refer to the "Minimum distance from slider" section for minimum distance.

To reduce the risk of injury, never more than one slider should be held or transported by the same person without packaging.



Pacemaker / Implanted heart defibrillator

Sliders could affect the functioning of pacemakers and implanted heart defibrillators. For the duration of a strong approach to a magnetic field, these devices switch into test mode and will not function properly.

- If you wear one of those devices keep the following minimum distances between the pacemaker / defibrillator and slider:
 - Min. 250 mm (10") for slider Ø 27 mm and 28 mm (PL01-27 / 28 / PL10-28)
 - Min. 150 mm (6") for slider Ø 19 mm and 20 mm (PL01-19 / 20)
 - Min. 100 mm (4") for slider Ø 12 mm (PL01-12)
- Inform others who wear these devices to comply with these minimum distances!



Caution - Risk of Electric Shock !

Before working, make sure that there are no high voltages.



Fast-moving machine parts

The sliders of LinMot linear motors are fast-moving machine parts. All necessary precautions must be taken to prevent persons approaching the moving elements during operation (provide covers, guards, etc.).



Automatic restart

The motors can start automatically under certain circumstances!

If necessary, a corresponding warning symbol must be provided and protection against entering the hazardous area or a suitable safe electronic disconnection must be provided!



Risk of injury due to a defect or fault

For areas where a defect or fault can result in substantial property damage or even serious personal injury, additional external precautions must be taken or devices must be installed to ensure safe operation even if a defect or fault occurs (eg. suitable safe electronic disconnection, mechanical interlocks, barriers, etc.).



Magnetic field

Magnets integrated in the sliders produce a strong magnetic field. They could damage TVs, laptops, computer hard drives, credit and ATM cards, data storage media, mechanical watches, hearing aids, and speakers.

- Keep magnets away from devices and objects that could be damaged by strong magnetic fields.
- For the above mentioned objects, keep a minimum distance as described in the "Pacemaker / implanted defibrillator" section.
- For non-anti-magnetic watches, keep the double minimum distance.

**Combustibility**

When machining magnets, the drilling dust could easily ignite. Machining the sliders and the magnets they contain is not permitted.

**Burn hazard**

The sliders of LinMot motors can reach temperatures of 80 °C, which may cause burns upon contact.

**Grounding**

All metal parts that are exposed to contact during any user operation or servicing and likely to become energized shall be reliably connected to the means for grounding.

**Mechanical handling**

Neodymium magnets are brittle and heat-sensitive. Machining the sliders and the magnets they contain is not permitted.

- Colliding magnets could crack. Sharp splinters could be catapulted for several meters and cause eye injury.
- By machining the sliders, heat would result which demagnetises the magnets.

**Slider**

Linear motor sliders consist of a high-precision, thin-walled stainless steel tube in which the neodymium magnets are housed. The LinMot sliders should be handled with care. Avoid contact with other sliders or iron parts as this can damage the magnets and the slider surface. Do not grip the sliders with pliers, as this can also damage the surface. Do not use sliders which are already damaged on the surface (scratches, deformation, etc.). This can cause further damage to the stator.

**Effects on people**

According to the current level of knowledge, magnetic fields of permanent magnets do not have a measurable positive or negative effect on people. It is unlikely that permanent magnets constitute a health risk, but it cannot be ruled out entirely.

- For your own safety, avoid constant contact with magnets.
- Store large magnets at least one meter away from your body.

**Temperature resistance**

Keep slider away from unshielded flame or heat. Temperature above 120°C will cause demagnetization.

3 Installation instructions

3.1 Operating conditions

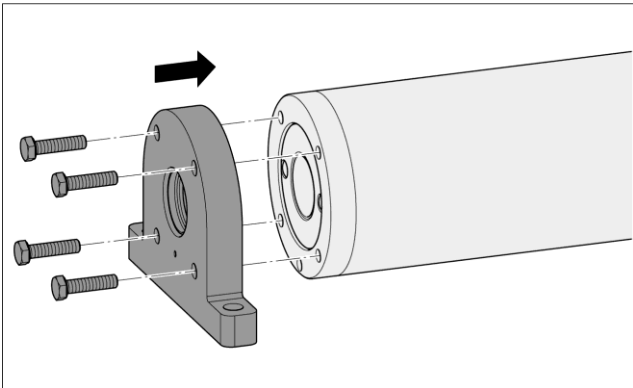


- Maximum ambient temperature limits are 10 °C...80 °C.
- Internal temperature sensor error occurs at 90 °C.
- The linear motor should not be operated under water.

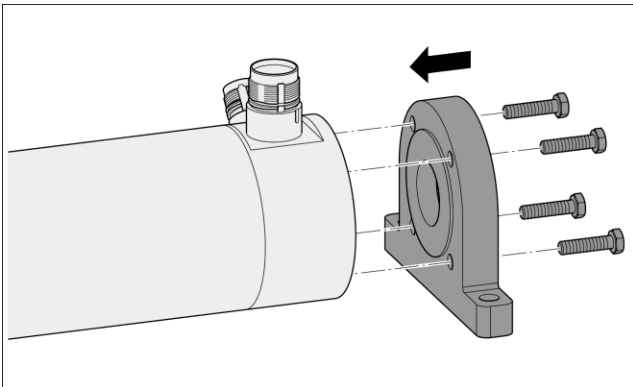
3.2 Instructions for installing the linear motor



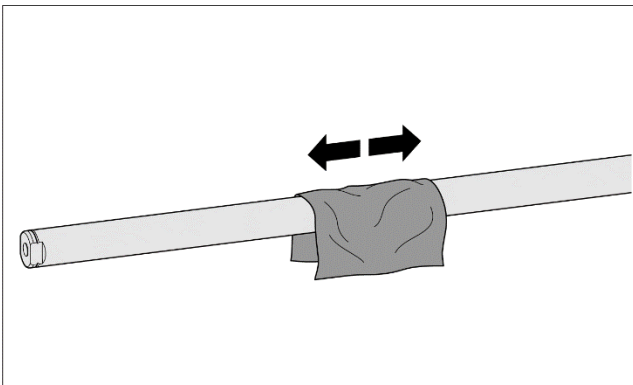
Please attend to the safety instructions in chapter 2 during the assembling!



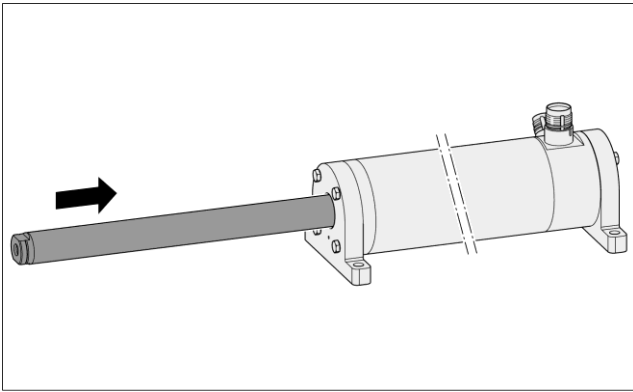
1. Install the mounting flange at the front.



2. Install the mounting flange at the rear.



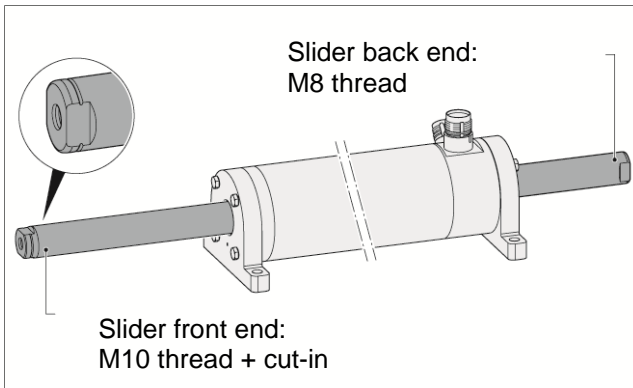
3. Clean the slider with a paper towel.



4. Insert the slider in the defined direction (see Assembly step 5.).



Large magnetic attraction forces
(Observe warning notice from page 5)!
If necessary, cover obvious iron constructions
with non-magnetic material (e.g. wood).

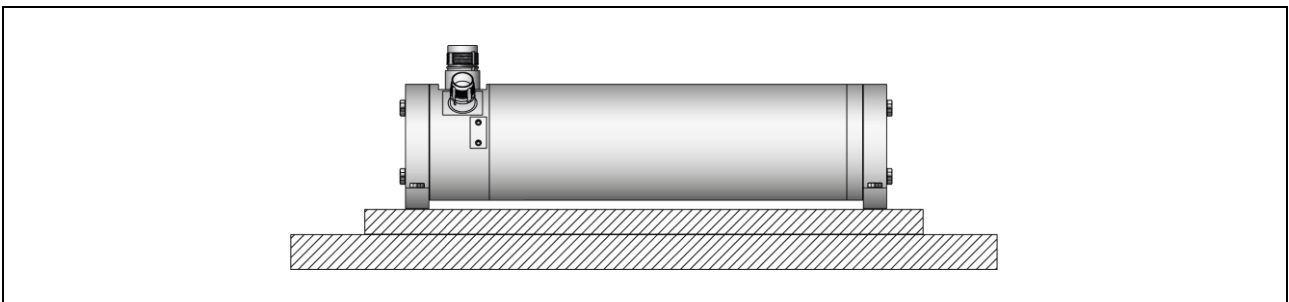


5. **Checking the installed direction of slider**
After the installation, the front end of the slider with M 10 thread and cut-in is located at the opposite side of the stator from the cable exit.



Slider back end should not be used for load mounting!

3.3 Mounting the stator



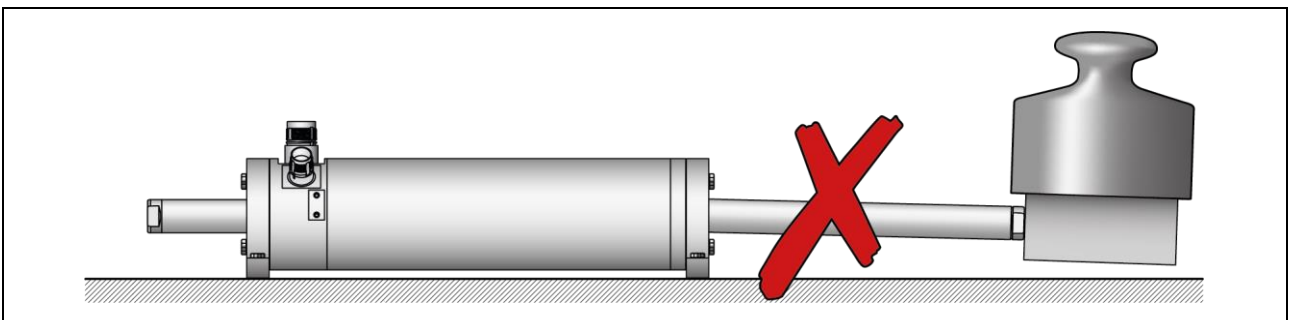
The motor is levelled and fixed to the ground using the holes in the flange foot.
The hole pattern is shown in section 9.1 "Stator Dimensions".

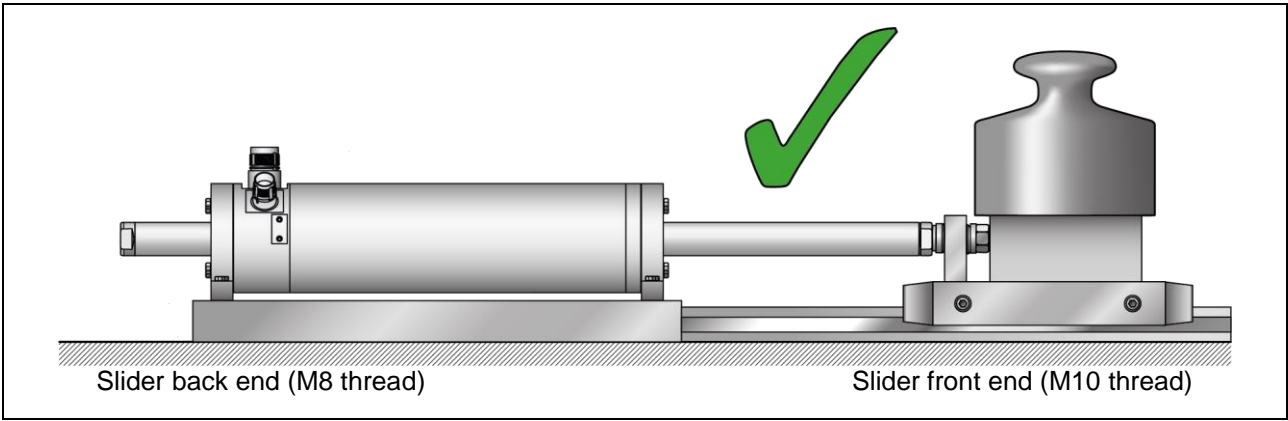
3.4 Mounting the payload to the slider

The load is mounted as a fixed bearing using spherical washers and conical seats (see the section 6.3).

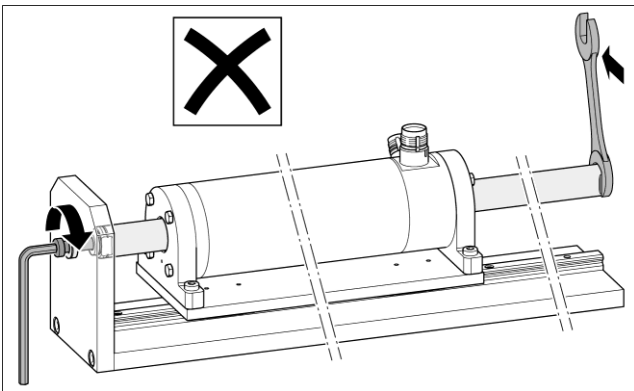


- To avoid shear force on slider and wear on stator, the payload has to be beared by a linear guide.
- Slider back end (M8 internal thread) should not be used for load mounting.

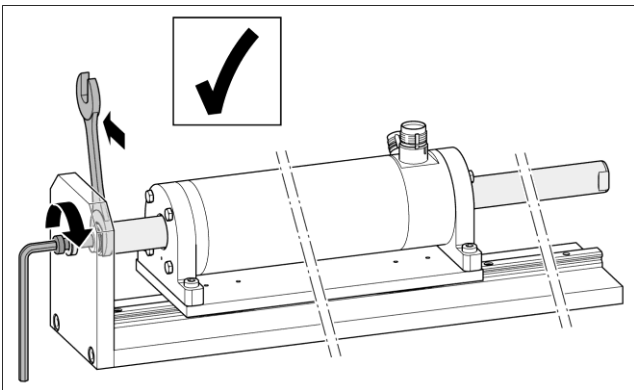




When attaching the load, the wrench for tightening the load must be used only on the load-facing side of the slider. Avoid torsional stress on slider (note the following figures).



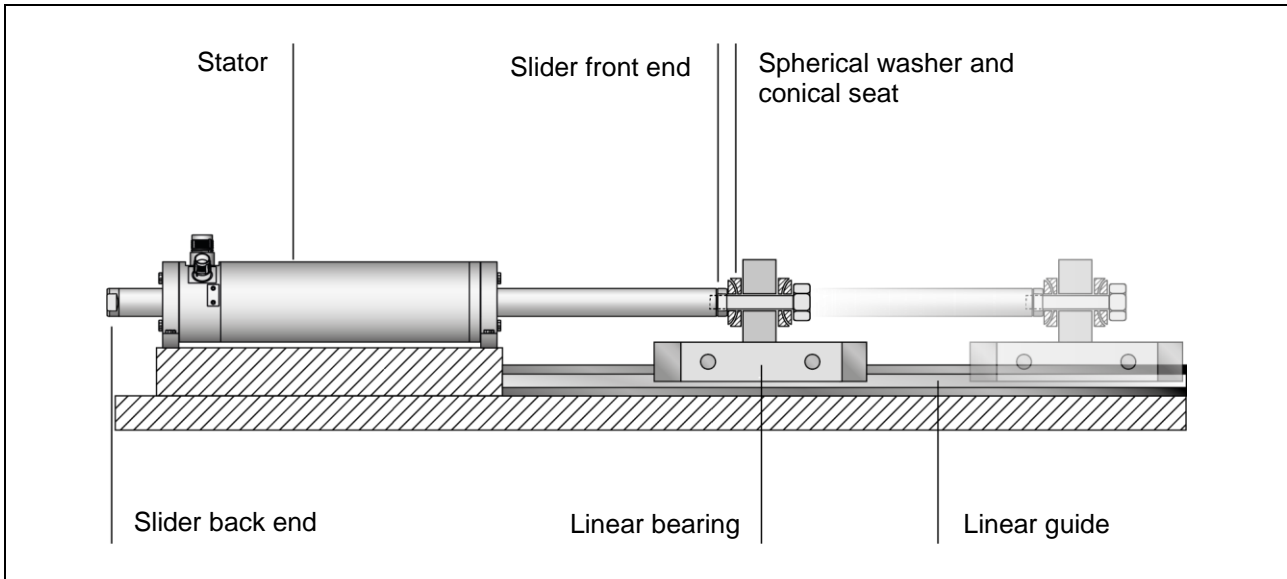
Incorrect mounting
Torsional stress on slider!



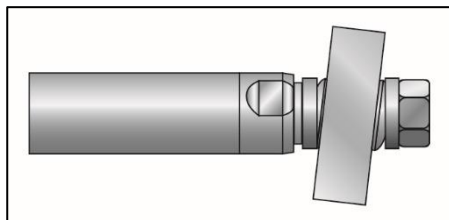
Correct mounting

Slider	Thread	Max. torque for screw (Dry)
28 mm	M 8 (Slider back end)	22.5 Nm
	M 10 (Slider front end)	42 Nm

3.5 "Moving slider" installation

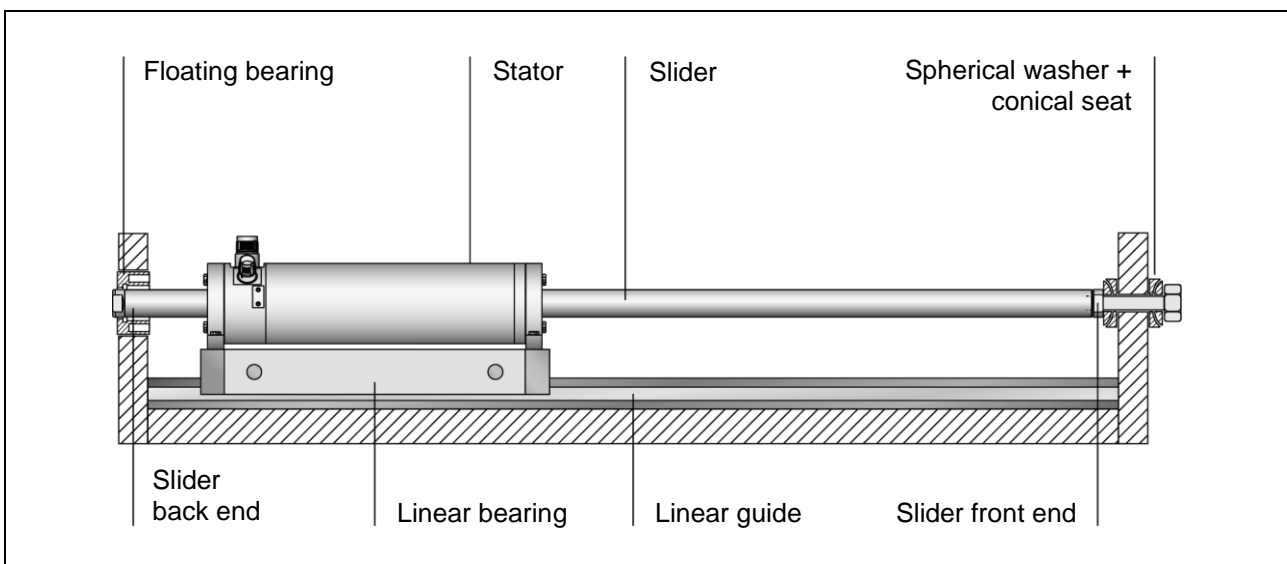


In a "moving slider" installation, the stator is fixed and the slider is the moving part. The load, borne by a linear guide, is attached directly to the end of the slider. In order to compensate for misalignment, spherical axial bearings consisting of spherical washers and conical seats (see the section Slider mounting kits) are used to connect to the load. The mounting kit of slider and an oversized hole for the screw make it possible to adjust a radial and angle offset.



Mounted payload with radial and angle offset.

3.6 "Moving stator" installation



In "moving stator" applications, the slider is fixed and the stator is the moving part. The load is attached to the stator, which is mounted on a linear guide. In order to avoid an overconstrained bearing mount and compensate for alignment errors, the slider may be mounted on one end in a fixed bearing with a spherical axial bearing. On the opposite end, the slider is mounted in a floating bearing. Mounting kits are available for mounting the slider (see the section Slider mounting kits).

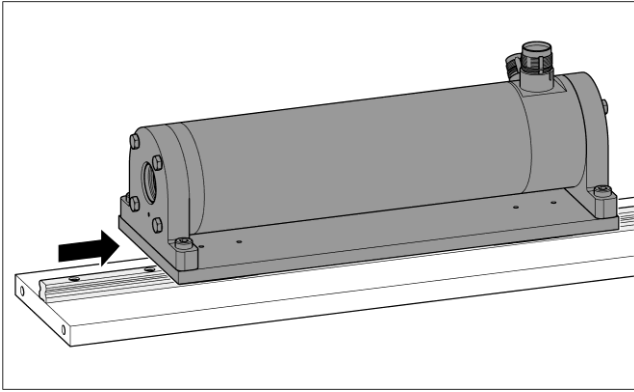
3.6.1 Assembling instruction



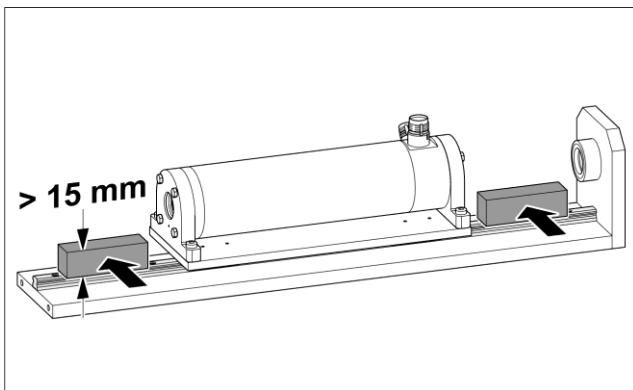
Please attend to the safety instructions in chapter 2 during the assembling!



If moving stator application is used, the minimum bending radius of the motor cable should be adhered to. See chapter Cable, section Technical Data.

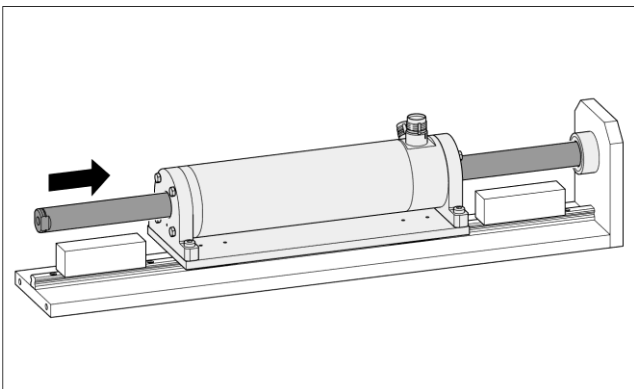


1. Mount stator to its support bearing.

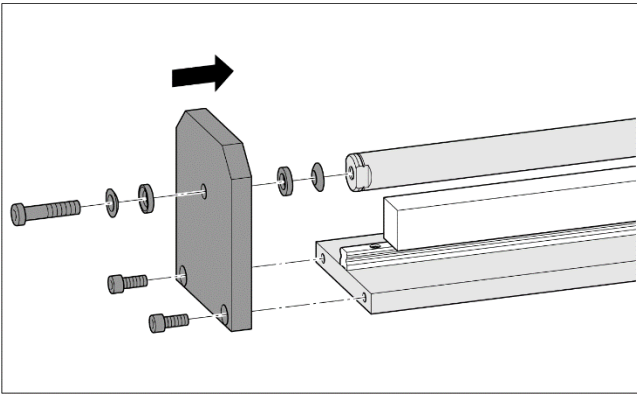


2. Placing a spacer.

Put a spacer (wood, plastic, aluminium with thickness 15 mm) between slider and linear guide. The spacer prevents injuries to the hands and damage to the slider surface!



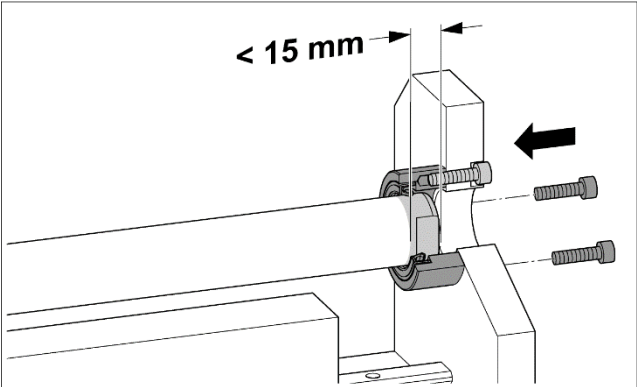
3. Insert slider into stator.



- 4. Installing the slider using the fixed bearing**
The fixed bearing is screwed to the front end of the slider.



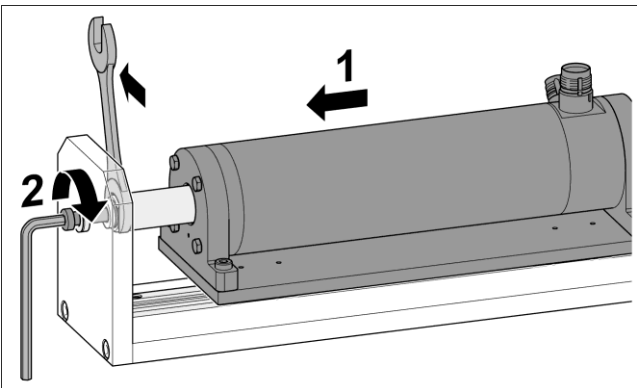
Do not tighten the screw yet!



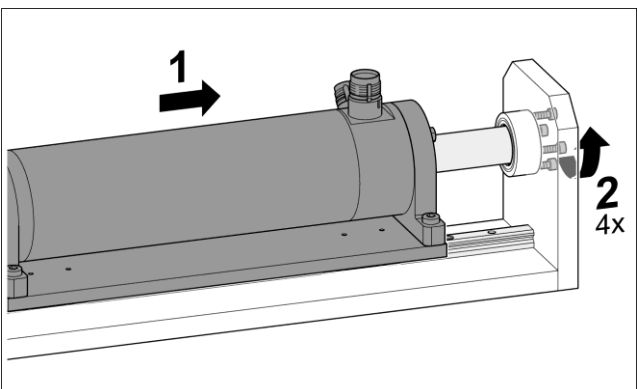
- 5. Mount floating bearing**



Do not tighten the screw!
The slider is allowed to extend into the floating bearing no more than 15 mm!



- 6. Move stator (back end) to the fixed end of slider, center slider in stator and tighten the screw.**



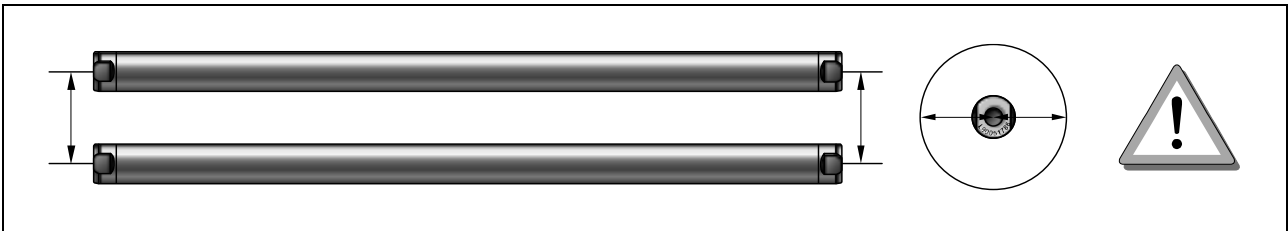
- 7. Move stator (front side) to the floating bearing and tighten screws.**



After the installation of the slider a safety label must be placed close to the slider.

3.7 Minimum distance from slider

3.7.1 Minimum distance from slider to slider

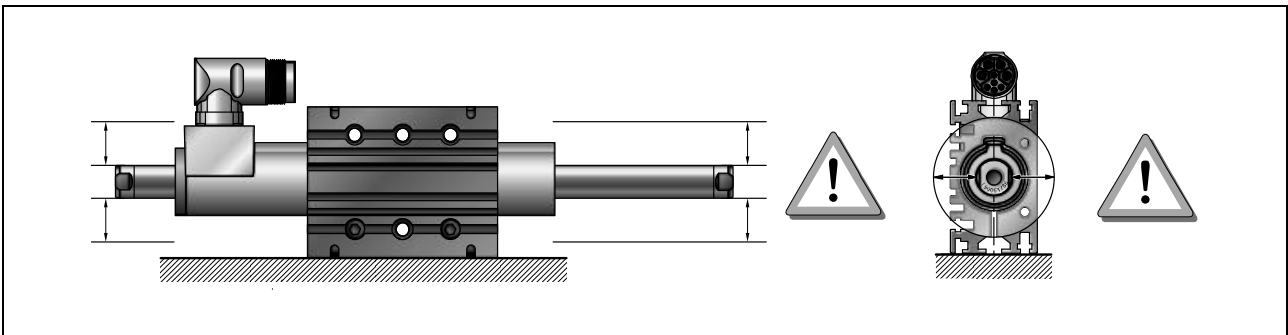


The sliders are made of neodymium magnets and have a strong magnetic attraction. It must be kept a minimum distance between the sliders. This minimized the risk of bruising and secondly, the sliders do not influence each other through their magnetic fields.

Type of slider	PL01	PL01-20 / PL01-19	PL01-28 / PL01-27	PL10-28
PL01-12	30 mm (1.18 in)			
PL01-20 / PL01-19		50 mm (1.97 in)		
PL01-28 / PL01-27			80 mm (3.15 in)	
PL10-28				70 mm (2.76 in)

The data are measured from slider center to slider center.

3.7.2 Minimum distance from slider to metallic parts



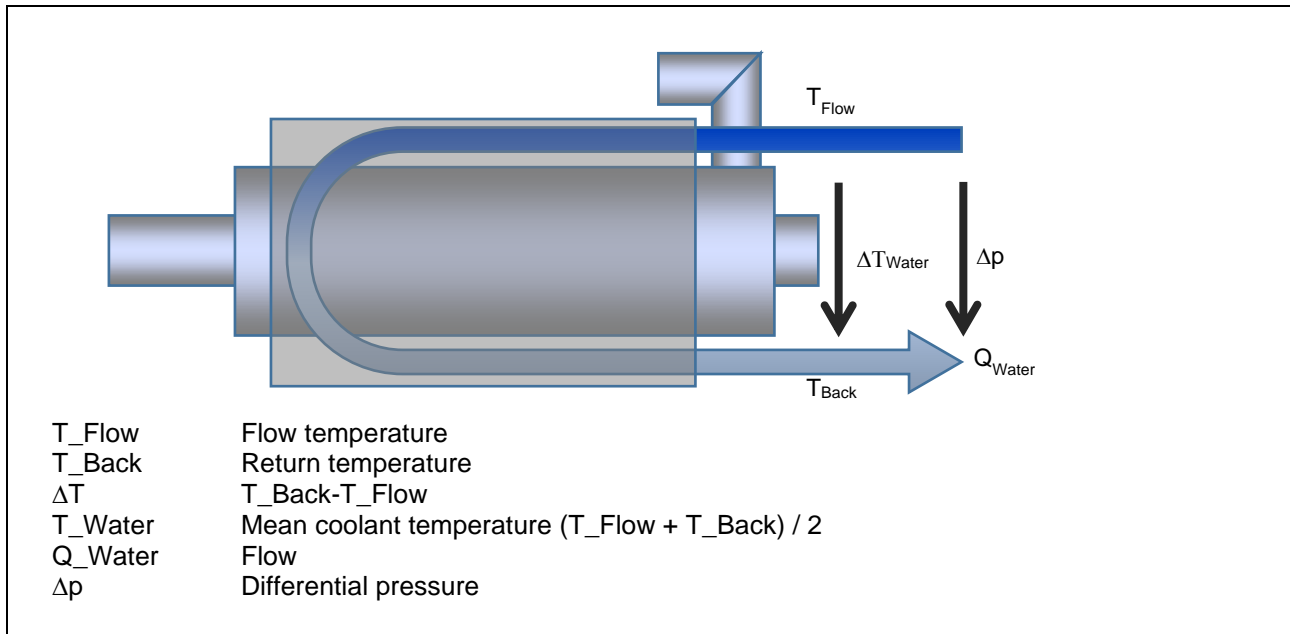
When installing linear motors in modules with metal parts near the slider, undesired forces can arise due to magnetic attraction or eddy currents. These generally manifest as erratic and jerky positioning, or reduced dynamics of the linear motor. In order to avoid this, minimum distances between the slider and any metal parts are to be observed whenever metal materials are used nearby.

Linear Motor	Minimum distance from slider surface to ferromagnetic parts (iron, steel, etc.)	Minimum distance from slider surface to non-ferromagnetic metallic parts (aluminum, bronze, stainless steel, etc.)
P10-70x...	20 mm	10 mm

4 Fluid cooling

With liquid cooling, the heat dissipated in the motor is carried away by the cooling medium (e.g. water). Compared to self-cooling, the continuous rated power of the motor is increased many times over.

4.1 Design of water cooling



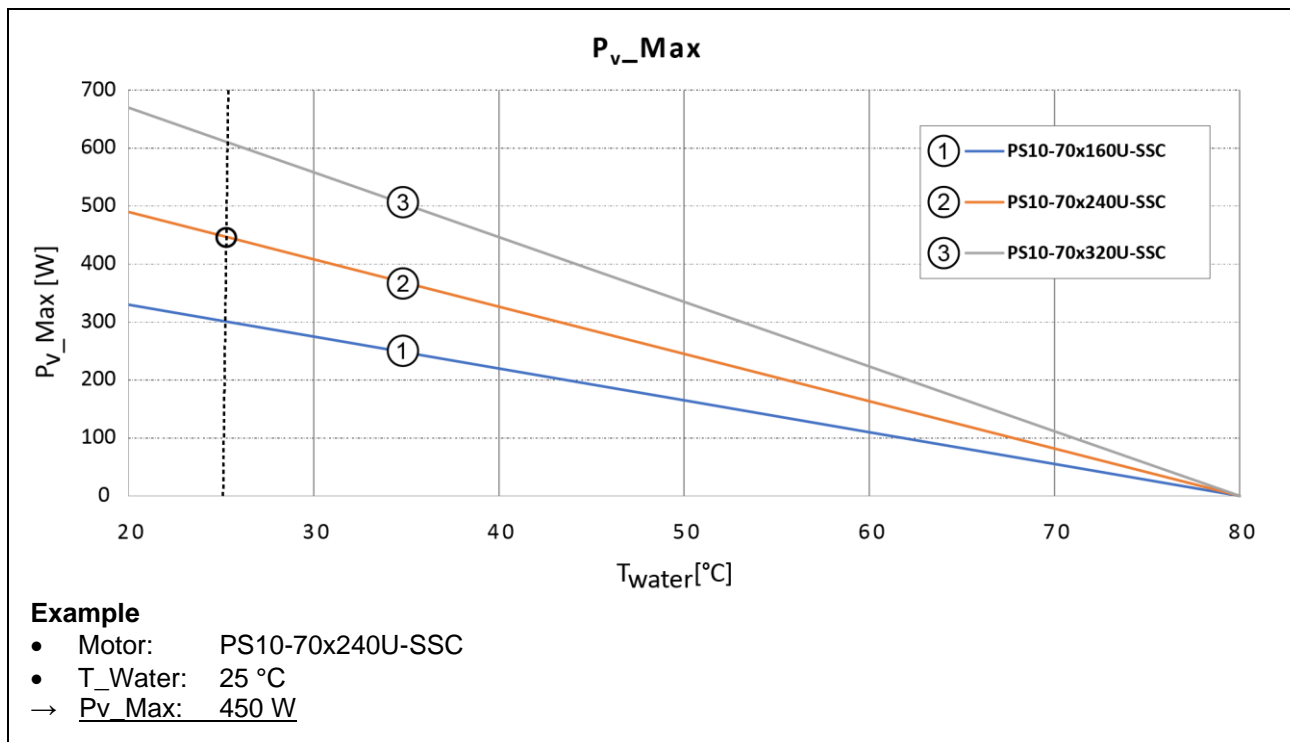
With the fluid cooling, the coolant is passed through the cooling circuit of the motor flange. Starting from the adjusted mean coolant temperature T_{Water} all other parameters of the cooling circuit may be dimensioned based on the diagrams referred to:

$T_{Water} \rightarrow P_{v_Max} \rightarrow Q_{Water} \rightarrow \Delta p$

The design is illustrated by an example in the following.

4.1.1 Determination of the max. possible amount of cont. power dissipation P_{v_Max}

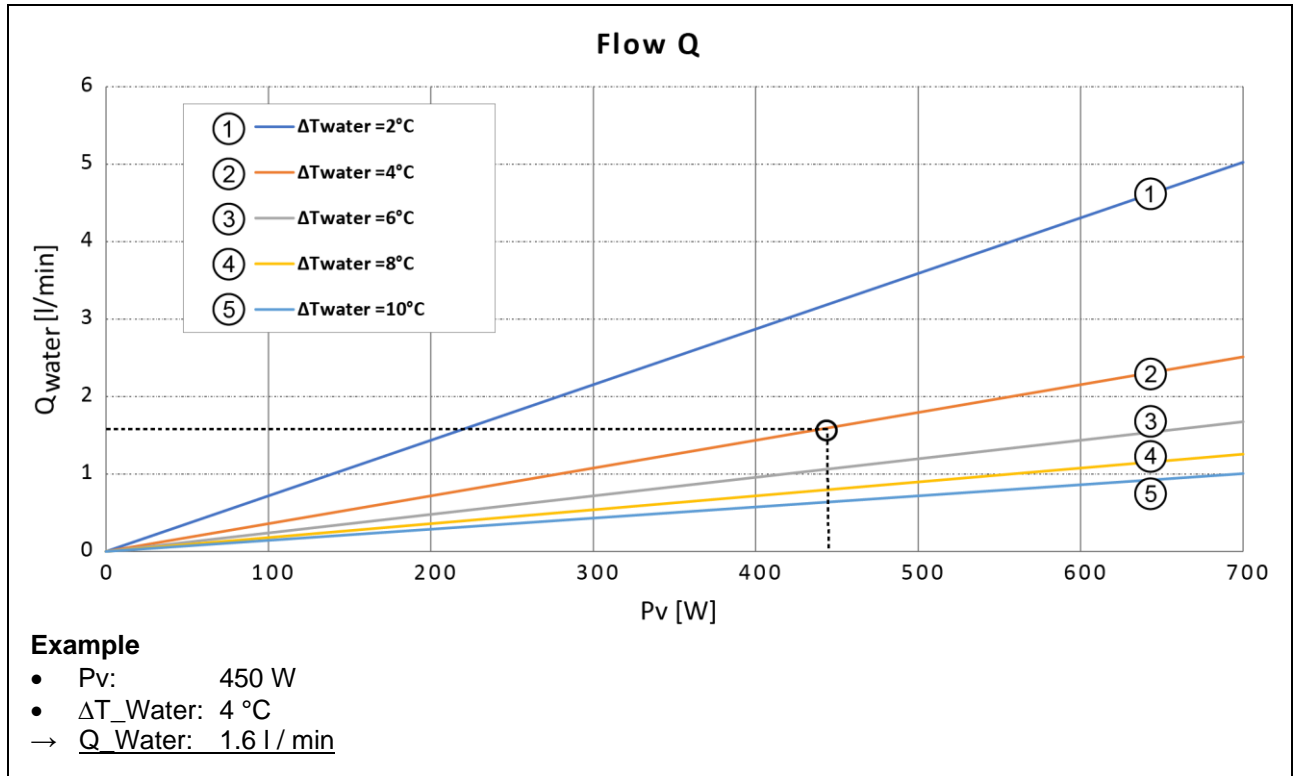
First, the average temperature of the cooling water is set. The supply temperature will be slightly lower and the return temperature slightly higher. Depending on the motor and the selected water temperature, the maximum motor losses that need to be dissipated by the cooling result.



- If the temperature of the cooling liquid is chosen to be lower than the ambient temperature, there is a risk of condensation.
- When used and stored in a frost-prone area, corrosion protection (e.g. Clariant) has to be added.

4.1.2 Determination of water flow Q

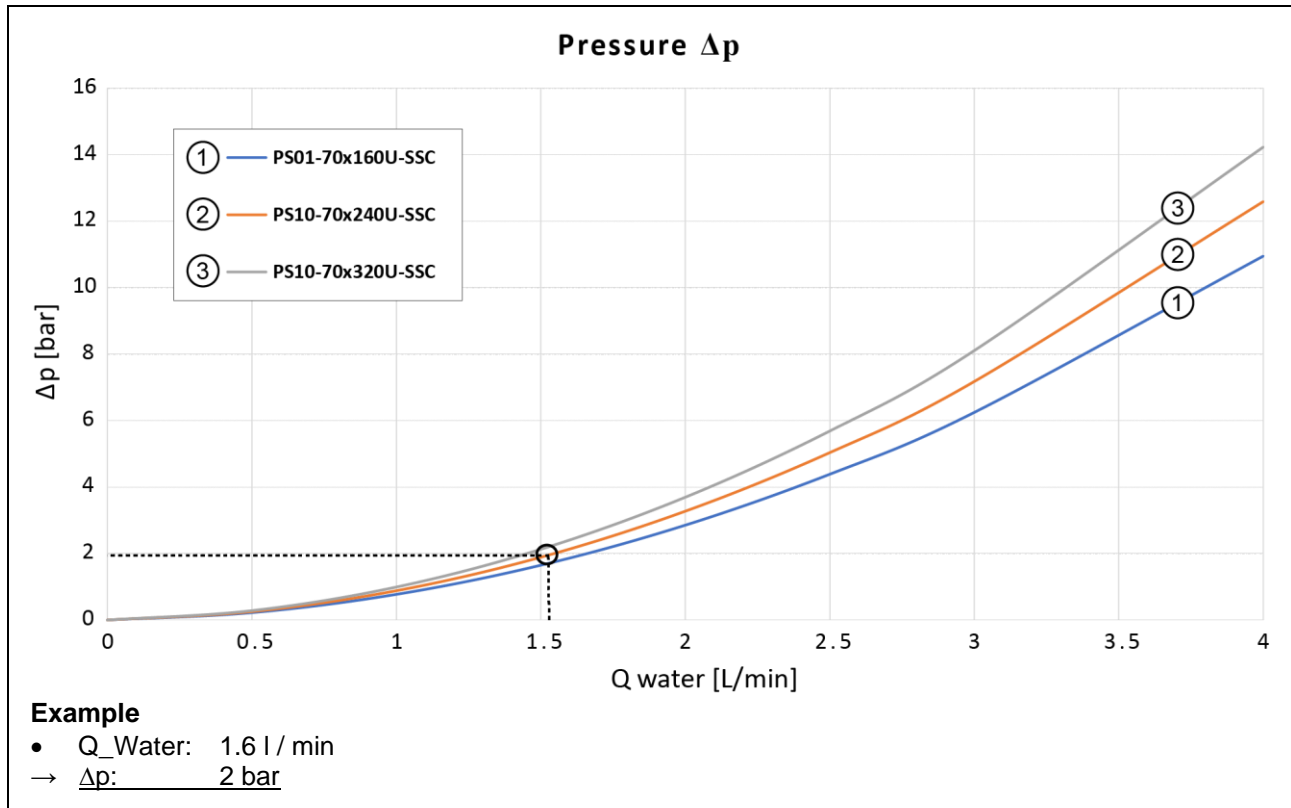
Depending on the selected difference between return and flow temperature, the required water flow rate is calculated from the max. power loss determined in 4.1.1.



To achieve a very regular cooling of the motor, the max. difference between flow and return temperature should not exceed 10 ° C.

4.1.3 Determination of water pressure Δp

To achieve the water flow rate determined in 4.1.2, the hydraulic resistance of the cooling circuit in the motor must be overcome. The maximum pressure difference across the motor's water connections can be determined from the following diagram, which depends not only on the flow rate but also on the type of motor.



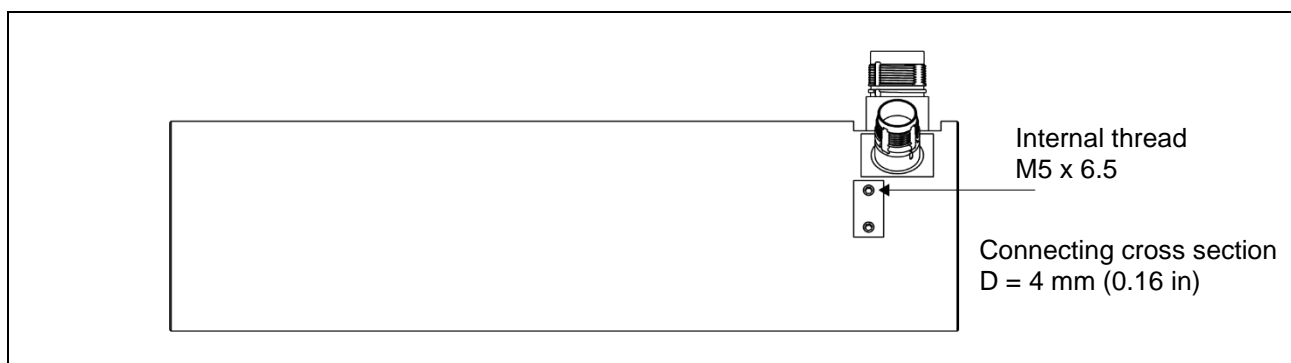
4.2 Corrosion protection

It is advised to add a corrosion protection into the cooling medium (water). A suitable agent can be, for example, Protectogen C Aqua by Clariant. Information of the mixing ratio between the cooling medium and the corrosion protection agent can be taken from the manufacturer's instructions.



- Mixing of various corrosion protection agents is to be avoided.
- Corrosion protection products must be matched to the materials of the cooling circuit (see table of materials in the cooling circuit).

4.3 Mounting



The supply or conduction of the cooling medium to the stator is carried out via two connecting thread (see illustration above). The connection can be realized by M5 push-in fittings.

5 Electrical connection



Do not connect or disconnect motor when there is power on the servo drive.
Use only double-shielded original LinMot cable. Cables from other sources must be checked precisely before commissioning.
Incorrect connections can destroy the drive and stator.

5.1 Technical Data of Motor Cables

For the linear motors of the P10-70 series, different cable types are used for the power and signal supply, depending on the use of the drive type (LinMot or third-party manufacturer). All cables are high-flex cables (suitable for trailing chains) and are used for both fixed and moving applications.

Type	Power cable		Encoder cable	
	KPS15-04	KPS15-04/04	KSS05-02/08	KSS05-02/13
Application for	LinMot drives + Third-party drives	Third-party drives	LinMot drives	Third-party drives
Minimum bending radius for fixed installation	50 mm (2 in)	60 mm (2.36 in)	50 mm (2 in)	45 mm (1.75 in)
Minimum bending radius when moving	100 mm (4 in) No torsion	120 mm (4.72 in) No torsion	100 mm (4 in) No torsion	90 mm (3.54 in) No torsion
Max. Cable length	30 m (can be limited by the servo drive)			
Approval	UL / CSA 1000V	UL / CSA 1000V / 300V	UL / CSA 300V	UL / CSA 30V
Material	Wire isolation: TPE Jacket: PUR	Wire isolation: TPE Jacket: PUR	Wire isolation: TPE Jacket: PUR	Wire isolation: PE Jacket: PUR
Oil resistance	sehr gut	sehr gut	sehr gut	sehr gut
Chemical resistance (to acids, alkalis, solvents, hydraulic fluid)	good	good	good	good
Outdoor durability	very good	very good	very good	very good
Flammability	flame retardant	flame retardant	flame retardant	flame retardant

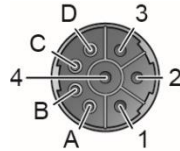
5.2 Stator connector assignment



Do not connect or disconnect motor when there is power on the servo drive.
Use only original LinMot cable. Cables from other sources must be checked precisely before commissioning.
Incorrect connections can destroy the drive and stator.

5.2.1 Power Connector

Shielded motor cable $d = 1.5 \text{ mm}^2$



Pin	P10-70-SSC	P10-70-SSC-D04	P10-70-SSC-D05	Wire Color Motor Cable
1	Phase U	Phase U	Phase U	red
2	PE	PE	PE	yellow-green
3	Phase W	Phase W	Phase W	black
4	Phase V	Phase V	Phase V	blue
A	n.c.	Pt1000+ ¹⁾	PTC+ ¹⁾	purple
B	n.c.	Pt1000- ¹⁾	PTC- ¹⁾	grey
C	n.c.	n. c.	n. c.	yellow
D	n.c.	n. c.	n. c.	brown

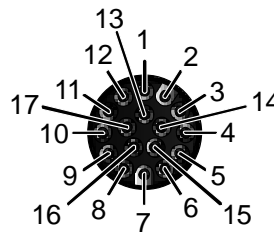
Pin	P10-70-SSC-D24 P10-70-SSC-D24S	P10-70-SSC-D25 P10-70-SSC-D25S	P10-70-SSC-D26	Wire Color Motor Cable
1	Phase U	Phase U	Phase U	red
2	PE	PE	PE	yellow-green
3	Phase W	Phase W	Phase W	black
4	Phase V	Phase V	Phase V	blue
A	Pt1000+ ¹⁾	PTC+ ¹⁾	Do not connect	purple
B	Pt1000- ¹⁾	PTC- ¹⁾	Do not connect	grey
C	n.c.	n. c.	n. c.	yellow
D	n.c.	n. c.	n. c.	brown

Pin	P10-70-SSC-D34	Wire Color Motor Cable
1	Phase U	red
2	PE	yellow-green
3	Phase W	black
4	Phase V	blue
A	Pt1000+ ¹⁾	purple
B	Pt1000- ¹⁾	grey
C	n.c.	yellow
D	n.c.	brown

¹⁾ The temperature evaluation circuit must have the same galvanic reference potential as the encoder circuit (supply). It should therefore be connected to the supply GND. For correct evaluation, the connection potentials of the emulated temperature sensor must be in the range of the supply potentials. Valid temperature values can only be measured 50ms after the encoder supply is applied. In currentless state a resistance of 200kOhm is measured between pin A and B. The maximum voltage between pin A and B must not exceed 16VDC. The maximum current is 15mA.

5.2.2 Encoder Connector

Shielded twisted pair
Encoder Cable d = 0.5 mm² / 0.25 mm²



Pin	P10-70-SSC	Wire Color Motor Cable
1	+5VDC ¹⁾	red
2	GND	black
3	Sense +5V ¹⁾	white
4	Sense GND ¹⁾	brown
5	Motor Link C +	pink
6	Motor Link C -	grey
7	Sin +	yellow
8	Sin -	orange
9	Cos +	green
10	Cos -	blue
11 bis 17	n. c.	-

¹⁾ The supply voltage at 5V sense supply is approx. 6V. Newer motors are provided with a modified power supply, that does not require sense lines any more. In that case, a supply voltage of 6...9V is permitted.

Pin	P10-70-SSC-D04	P10-70-SSC-D05	Wire Color Motor Cable
1	3...13 VDC	3...13 VDC	white
2	GND	GND	brown
3	Vcc Sense (optional)	Vcc Sense (optional)	green
4	GND Sense (optional)	GND Sense (optional)	yellow
5	Do not connect	Do not connect	-
6	Do not connect	Do not connect	-
7	Sin +	Sin +	grey
8	Sin -	Sin -	pink
9	Cos +	Cos +	blue
10	Cos -	Cos -	red
11	Ref +	Ref +	black
12	Ref -	Ref -	violett
13	Hall U	Hall U	grey-red
14	Hall V	Hall V	red-blue
15	Hall W	Hall W	white-green
16	Temp+ (Pt1000 Char.) ²⁾	Temp+ (PTC 400/20k Char.) ²⁾	yellow-brown
17	Temp- (Pt1000 Char.) ²⁾	Temp- (PTC 400/20k Char.) ²⁾	white-yellow

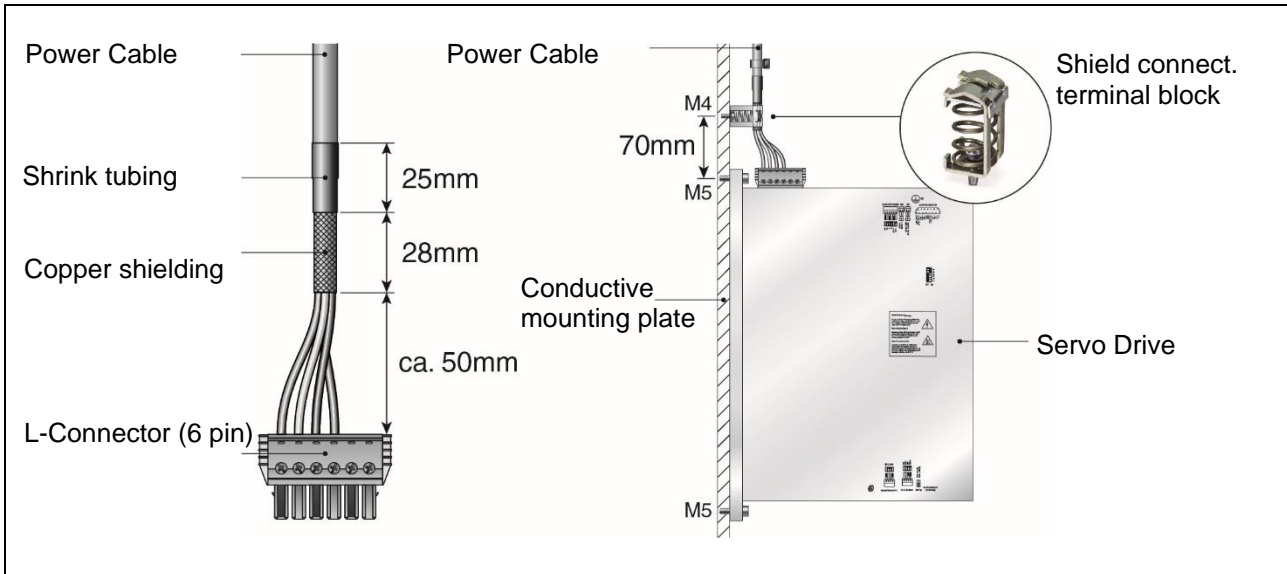
²⁾ The temperature evaluation circuit must have the same galvanic reference potential as the encoder circuit (supply). It should therefore be connected to the supply GND. For correct evaluation, the connection potentials of the emulated temperature sensor must be in the range of the supply potentials. Valid temperature values can only be measured 50ms after the encoder supply is applied. In the currentless state, a resistance of 200kOhm is measured between pin 16 and 17 is measured. The maximum voltage between pin 16 and 17 must not exceed 16VDC. The maximum current is 15mA.

Pin	P10-70-SSC-D24 P10-70-SSC-D24S	P10-70-SSC-D25 P10-70-SSC-D25S	P10-70-SSC-D26	Wire Color Motor Cable
1	3...13 VDC	3...13 VDC	3...13 VDC	white
2	GND	GND	GND	brown
3	Vcc Sense (optional)	Vcc Sense (optional)	Vcc Sense (optional)	green
4	GND Sense (optional)	GND Sense (optional)	GND Sense (optional)	yellow
5	Do not connect	Do not connect	Do not connect	–
6	Do not connect	Do not connect	Do not connect	–
7	A	A	A	grey
8	/ A	/ A	/ A	pink
9	B	B	B	blue
10	/ B	/ B	/ B	red
11	Ref	Ref	Ref	black
12	/ Ref	/ Ref	/ Ref	violett
13	Hall U	Hall U	Hall U	grey-red
14	Hall V	Hall V	Hall V	red-blue
15	Hall W	Hall W	Hall W	white-green
16	Temp+ (Pt1000 Char.) ¹⁾	Temp+ (PTC 400/20k Char.) ¹⁾	Temp+ (PTC 400/20k Char.) ¹⁾	yellow-brown
17	Temp- (Pt1000 Char.) ¹⁾	Temp- (PTC 400/20k Char.) ¹⁾	Do not connect	white-yellow

Pin	P10-70-SSC-D34	Aderfarbe Motorkabel
1	3...13 VDC	white
2	GND	brown
3	Vcc Sense (optional)	green
4	GND Sense (optional)	yellow
5	Do not connect	–
6	Do not connect	–
7	SO (Slave out)	grey
8	/ SO (Slave out)	pink
9	Do not connect	–
10	Do not connect	–
11	MA (Master clock)	black
12	/ MA (Master clock)	violett
13	Hall U	grey-red
14	Hall V	red-blue
15	Hall W	white-green
16	Temp+ (Pt1000 Char.) ¹⁾	yellow-brown
17	Temp- (Pt1000 Char.) ¹⁾	white-yellow

¹⁾ The temperature evaluation circuit must have the same galvanic reference potential as the encoder circuit (supply). It should therefore be connected to the supply GND. For correct evaluation, the connection potentials of the emulated temperature sensor must be in the range of the supply potentials. Valid temperature values can only be measured 50ms after the encoder supply is applied. In the currentless state, a resistance of 200kOhm is measured between pin 16 and 17 is measured. The maximum voltage between pin 16 and 17 must not exceed 16VDC. The maximum current is 15mA.

5.3 Attaching the cable shielding



The power cable is supplied with a copper shielding (see illustration above). This prevents electrical and / or magnetic fields. The shielded part of the cable must be grounded via a connection to the back wall of the switchboard. The shielding has to be mounted holohedral to the connection part (see scheme above). The shield connection terminal block is offered as an accessory for power cables and must be ordered separately (Item-No. 0150-3631) However, the kind of attaching the cable shielding generally depends on the system of the switchboard manufacturer.

5.4 Connectors

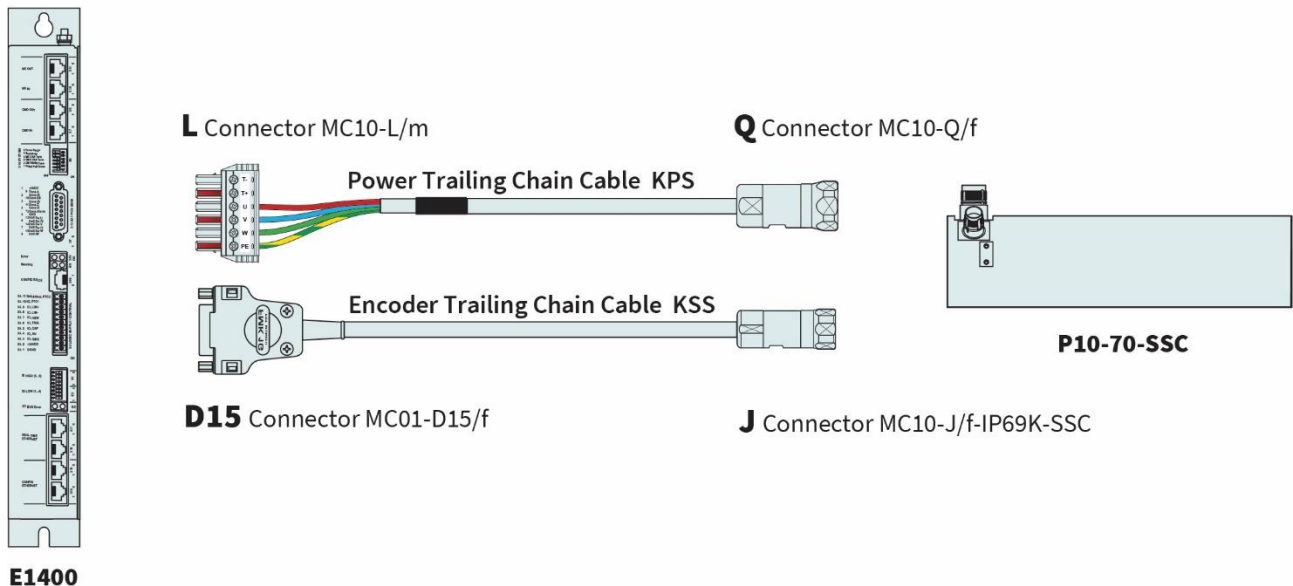
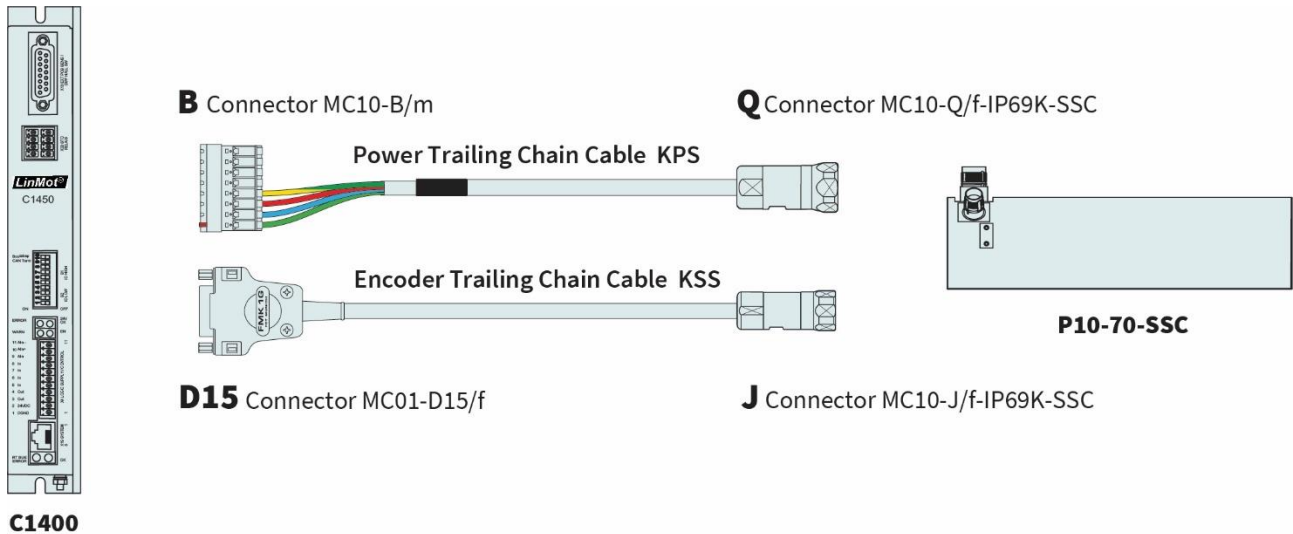
For a complete encapsulation the standard motor connector is welded to the housing of the stator. The connector is designed for tightening and vertically aligned (see the section „Stator dimensions“). Motor connector and cable connector are firmly bolted together. Dimensions and tightening torque are shown in the following figure.

	<p>Q-Connector 8-pin IP Code: IP69k Material: Stainless steel, Mat.-No. 1.4404 Max. torque: 0.6 Nm</p>	
<p>MC10-Q/f-IP69K-SSC</p>	<p>Connector power PS10-70-SSC, IP69K</p>	<p>Item-No. 0160-1166</p>

	<p>J-Connector 17-pin IP Code: IP69k Material: Stainless steel, Mat.-No. 1.4404 Max. torque: 0.6 Nm</p>	
<p>MC10k-J/f-IP69K-SSC</p>	<p>Connector encoder PS10-70-SSC, IP69K</p>	<p>Art.-Nr. 0160-1167</p>

6 Accessories

6.1 Motor Cables for use with LinMot Drives



For applications where IP69k protection is not required, the motors can also be operated with P10-70 standard cables and connectors.

Power Cables

Item	Description	Item-No.
KPS15-04-L/Q-SSC-	Power Trailing Chain Cable L/Q-SSC-, Custom length	0150-3858
KPS15-04-B/Q-SSC-	Power Trailing Chain Cable B/Q-SSC-, Custom length	0150-3863

Encoder Cables

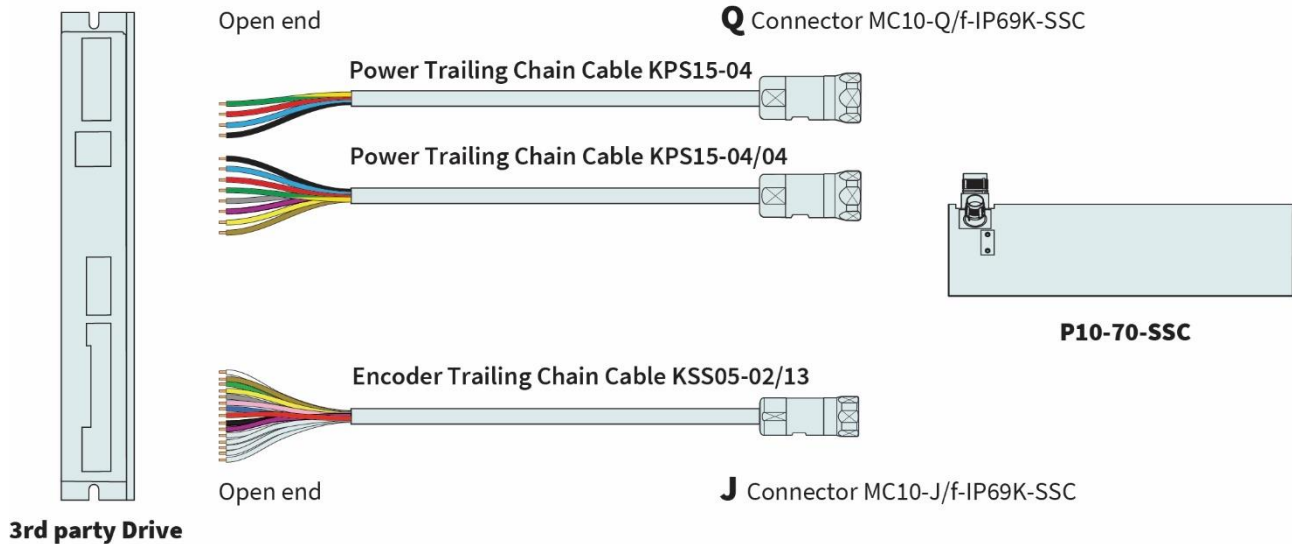
Item	Description	Item-No.
KSS05-02/08-D15(f)-45°/J-SSC-	Encoder Trailing Chain Cable D15/J-SSC-, Custom length	0150-3864

Connectors

Item	Description	Item-No.
MC10-L/m	Connector Power E1400/X2	0150-3382

MC01-D15/f	Motor Connector D15 (f)	0150-3136
MC10-Q/f-IP69K-SSC	Motor Connector Q/f, IP69K, SSC	0160-1166
MC10k-J/f-IP69K-SSC	Motor Connector J/f, IP69K, SSC	0160-1167

6.2 Motor Cables for use with third-party Drives



For applications where IP69k protection is not required, the motors can also be operated with P10-70 standard cables and connectors.

Order Overview

Dxx	Power Cable	Encoder Cable	Position Feedback	Temperature Feedback via Power Cable	Temperature Feedback via Encoder Ca.	Halls witch Signals	Ref. Signal
D04	KPS15-04-_/Q-...	KSS05-02/13-_/J-...	Sin/Cos 1Vpp	---	Pt1000	Hall U/V/W	Ref
	KPS15-04/04-_/Q-...	KSS05-02/13-_/J-...	Sin/Cos 1Vpp	Pt1000	Pt1000	Hall U/V/W	Ref
D05	KPS15-04-_/Q-...	KSS05-02/13-_/J-...	Sin/Cos 1Vpp	---	PTC	Hall U/V/W	Ref
	KPS15-04/04-_/Q-...	KSS05-02/13-_/J-...	Sin/Cos 1Vpp	PTC	PTC	Hall U/V/W	Ref
D24	KPS15-04-_/Q-...	KSS05-02/13-_/J-...	A/B 1µm	---	Pt1000	Hall U/V/W	Ref
	KPS15-04/04-_/Q-...	KSS05-02/13-_/J-...	A/B 1µm	Pt1000	Pt1000	Hall U/V/W	Ref
D24S	KPS15-04-_/Q-...	KSS05-02/13-_/J-...	A/B 5µm	---	Pt1000	Hall U/V/W	Ref
	KPS15-04/04-_/Q-...	KSS05-02/13-_/J-...	A/B 5µm	Pt1000	Pt1000	Hall U/V/W	Ref
D25	KPS15-04-_/Q-...	KSS05-02/13-_/J-...	A/B 1µm	---	PTC	Hall U/V/W	Ref
	KPS15-04/04-_/Q-...	KSS05-02/13-_/J-...	A/B 1µm	PTC	PTC	Hall U/V/W	Ref
D25S	KPS15-04-_/Q-...	KSS05-02/13-_/J-...	A/B 5µm	---	PTC	Hall U/V/W	Ref
	KPS15-04/04-_/Q-...	KSS05-02/13-_/J-...	A/B 5µm	PTC	PTC	Hall U/V/W	Ref
D26	KPS15-04-_/Q-...	KSS05-02/13-_/J-...	A/B 1µm	---	PTC SE	Hall U/V/W	Ref
	KPS15-04/04-_/Q-...	KSS05-02/13-_/J-...	A/B 1µm	PTC SE	PTC SE	Hall U/V/W	Ref
D34	KPS15-04-_/Q-...	KSS05-02/13-_/J-...	BiSS-C	---	Pt1000	Hall U/V/W	---
	KPS15-04/04-_/Q-...	KSS05-02/13-_/J-...	BiSS-C	Pt1000	---	Hall U/V/W	---

Power Cables

Item	Description	Item-No.
KPS15-04-_/Q-SSC-	Power Trailing Chain Cable P10-70...-SSC-Dxx, Custom length	0150-6127
KPS15-04/04-_/Q-SSC-	Power Trailing Chain Cable P10-70...-SSC-Dxx, Custom length	0150-6128

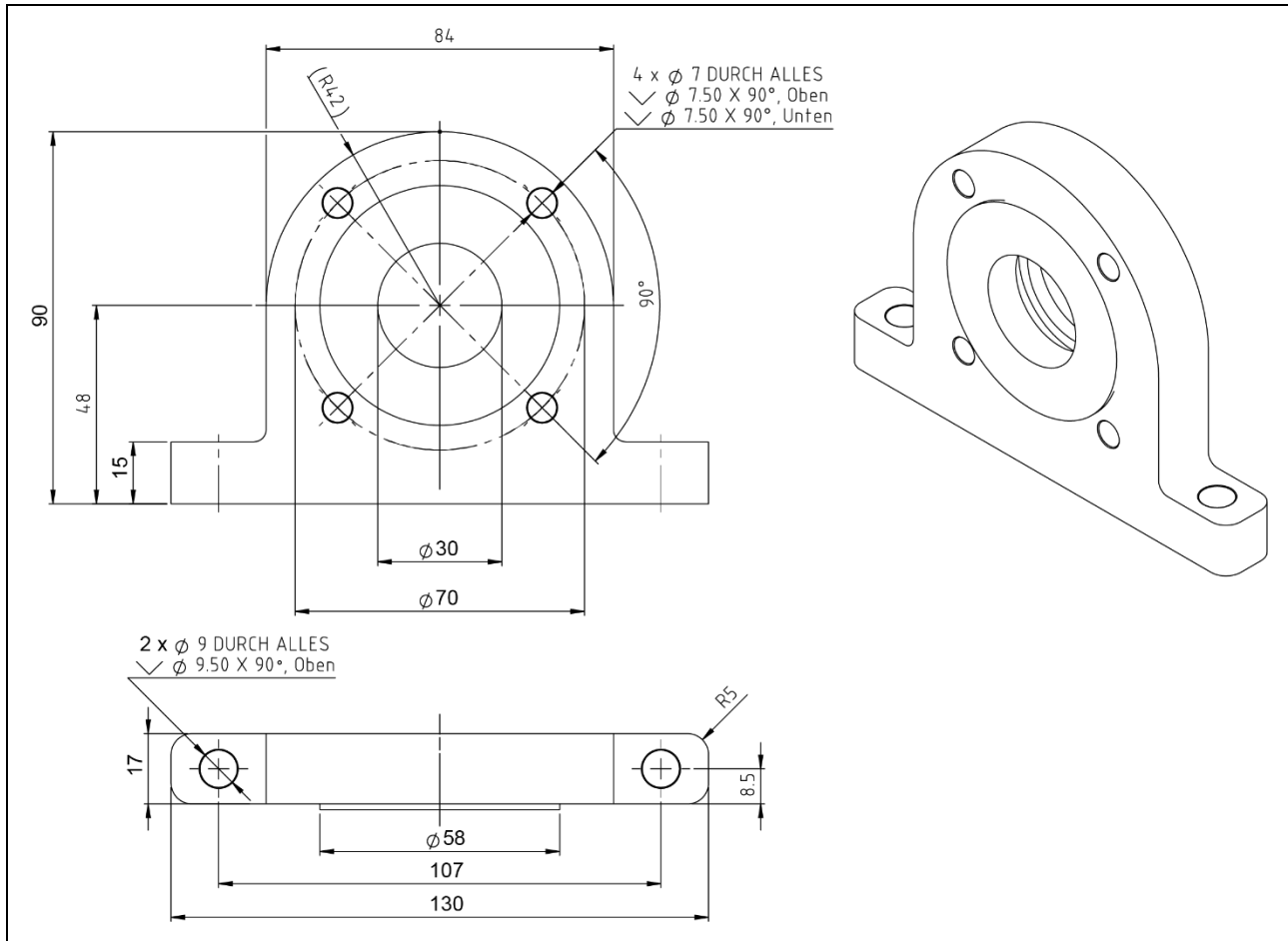
Encoder Cables

Item	Description	Item-No.
KSS05-02/13-./J-SSC-	Encoder Trailing Chain Cable ./J-SSC-, Custom length	0150-3866

Connectors

Item	Description	Item-No.
MC10-Q/f-IP69K-SSC	Motor Connector Q/f, IP69K, SSC	0150-1166
MC10-J/f-IP69K-SSC	Motor Connector J/f, IP69K, SSC	0150-1167

6.3 Mounting flange



The stainless steel mounting flange is attached to the front and rear of the stator. 4 hexagon bolts M6 x 25 are supplied for this purpose. A wiper ring is also integrated into the mounting flange. This ensures that the inside of the stator remains free of dirt.

To replace the wiper ring, this article can also be ordered separately.

Ordering information

Item	Description	Item-No.
PB13-70x17-SSC	Mounting flange with wiper and A4 screws	0150-3877
PAW01-28-BL-HPU-Lf	Wiper blue HPU low friction	0160-3432

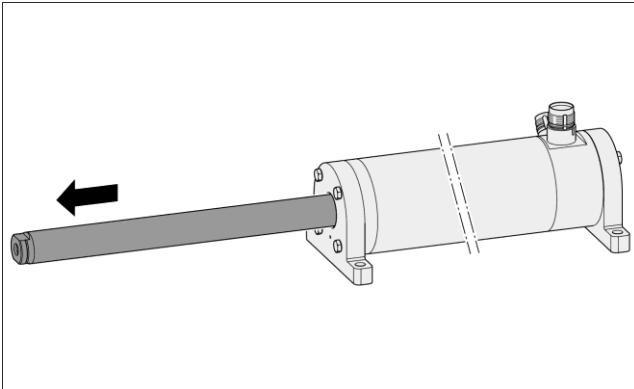
6.4 Bearing kit

6.4.1 General information

For fast, uncomplicated maintenance, these types of motors are equipped with replaceable slider bearings. The integrated sliding bearings are easy to replace in a few manual steps.

Item	Description	Item-No.
PB10-70x160-SSC-D	Bearing kit for PS10-70x160-SSC (dry bearing)	0150-3853
PB10-70x240-SSC-D	Bearing kit for PS10-70x240-SSC (dry bearing)	0150-3854
PB10-70x320-SSC-D	Bearing kit for PS10-70x320-SSC (dry bearing)	0150-3855

6.4.2 Mounting

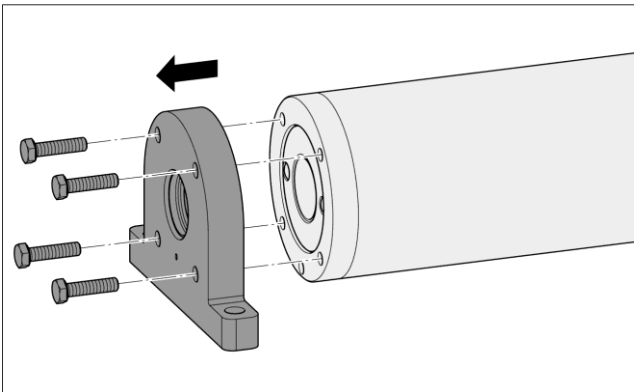


1. Remove the slider.

Pull the slider completely out of the stator.

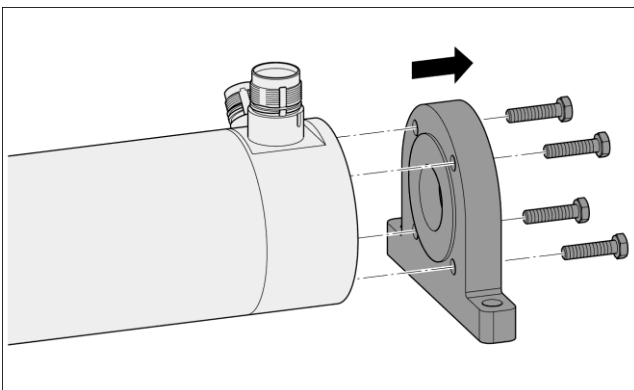


Large magnetic attraction forces
(Observe warning notice from page 5)!
If necessary, cover nearby ironwork with non-magnetic spacers (e.g. 20mm wooden board).



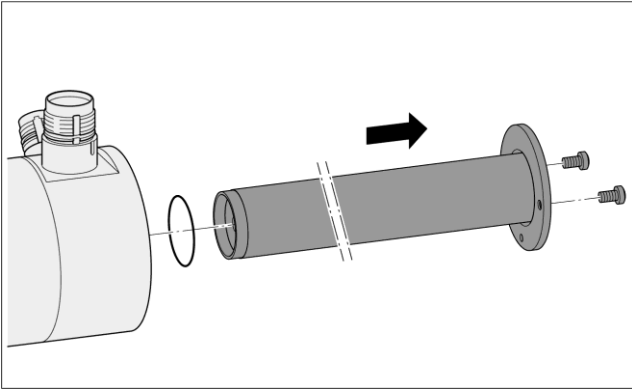
2. Dismantle the front mounting flange.

Loosen screws and remove flange.

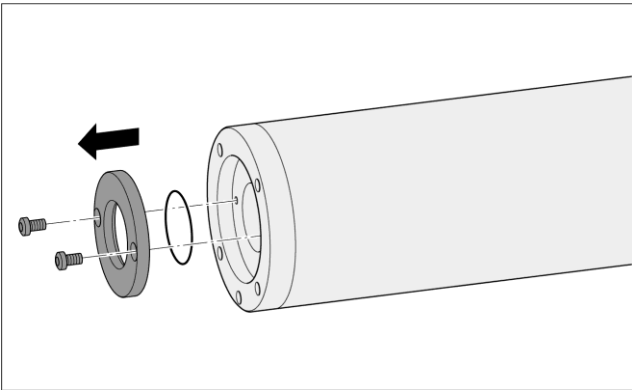


3. Dismantle rear mounting flange.

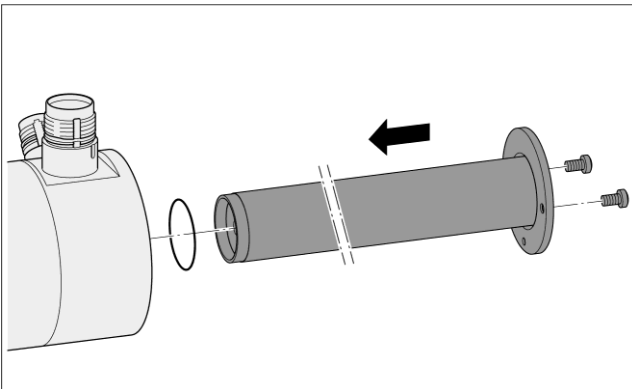
Loosen screws and remove flange.



- 4. Remove bearing tube.**
Loosen the screws and pull out the bearing tube on the rear side.

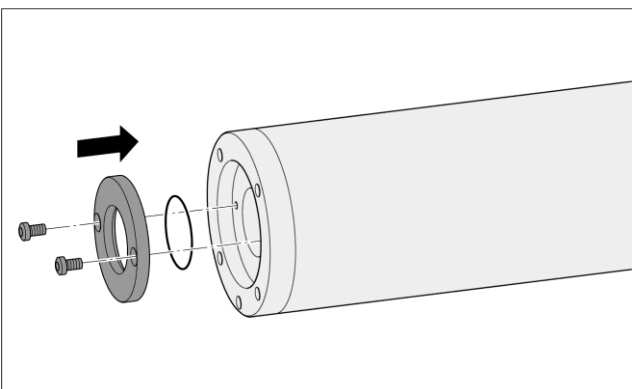


- 5. Remove the front end piece.**
Loosen the screws and remove the end piece.



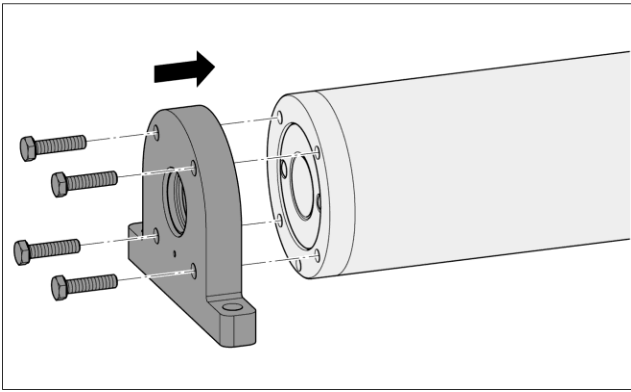
- 6. Mount a new bearing tube**
Insert the seal into the bearing tube groove and slide the bearing tube into the stator rear side. Then screw the bearing tube.

Tightening torque: 2.4 Nm



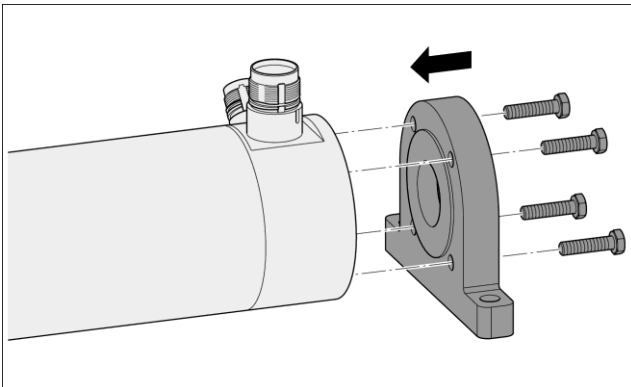
- 7. Mount a new end piece.**
Insert the seal into the groove and attach the end piece to the front of the stator. Then screw the end piece.

Tightening torque 2.4 Nm



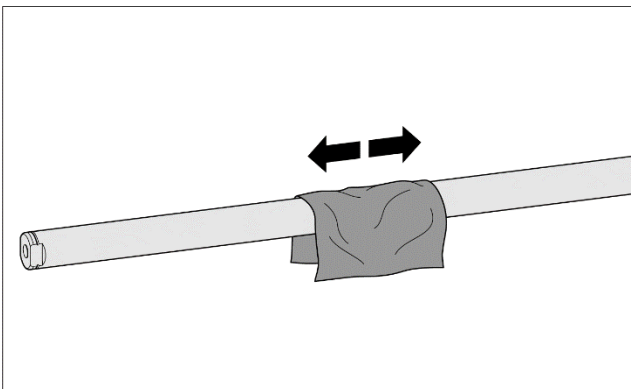
8. Mount the front mounting flanges.
Screw the mounting flange.

Tightening torque: 6 Nm

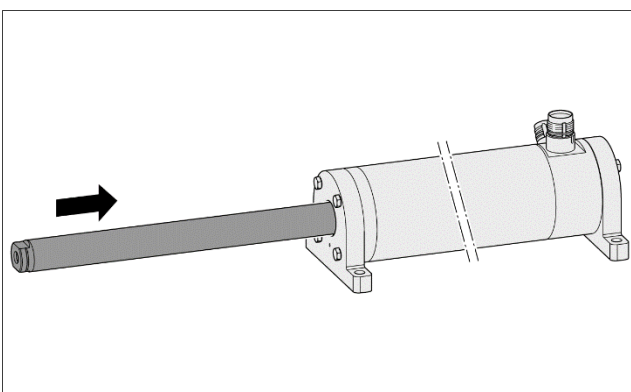


9. Mount the rear mounting flanges.
Screw the mounting flange.

Tightening torque: 6 Nm

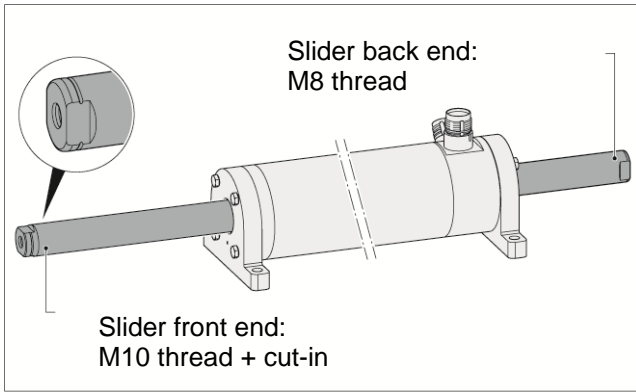


10. Clean the slider with a paper towel.



11. Insert the slider in the defined direction (see Assembly step 12.).

! Large magnetic attraction forces
(Observe warning notice from page 5)!
If necessary, cover nearby ironwork with non-magnetic spacers (e.g. 20mm wooden board).

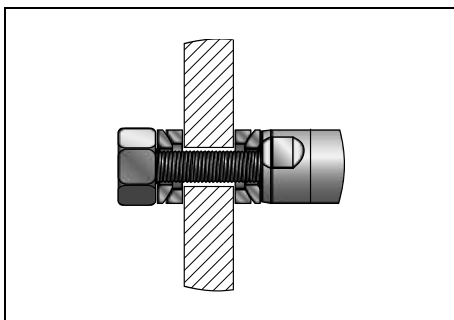


12. Checking the installed direction of slider
 After the installation, the front end of the slider with M 10 thread and cut-in is located at the opposite side of the stator from the cable exit.

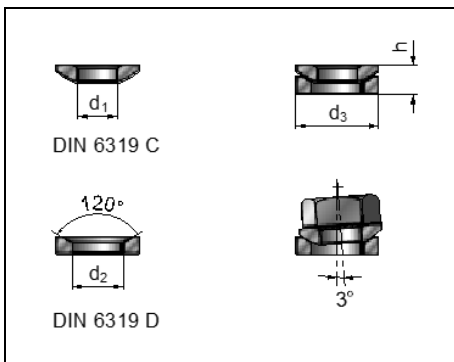
! Slider back end should not be used for load mounting!

6.5 Slider mounting kits

6.5.1 Fixed bearing



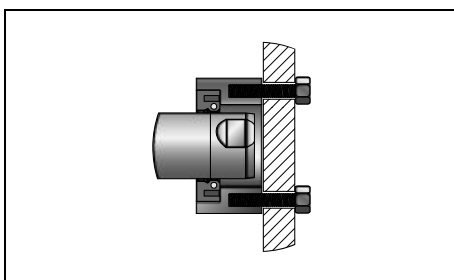
Slider mounting kit consists of a spring washer, a pair of spherical washers, and a pair of conical seats. It allows the slider to be fixed in the direction of motion. It also helps to compensate for radial and angle offset.



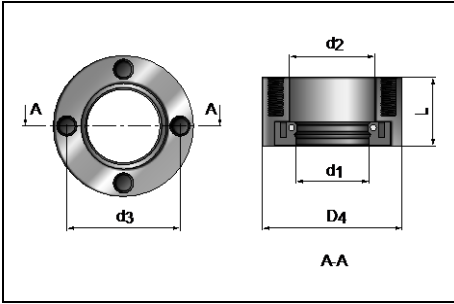
Material
 Spherical washer / conical seat: case hardened steel

Item	Item No.	Slider	Thread	d1	d2	d3	h
PLF01-28 (Stainless-st.)	0150-3297	28mm	M10	10.5mm (0.41in)	12mm (0.47in)	21mm (0.83in)	6.5mm (0.26in)

6.5.2 Floating bearing



Floating bearing assembly that permits radial adjustment of slider position and permits a small amount of radial and axial movement.



Material

Housing:
Bearing:

Stainless steel 1.4305
Nitrile butadiene rubber
Spring steel DIN17223

Item	Item No.	Slider	Thread	d1	d2	d3	D4	L
PLL01-28	0150-3094	28mm	M5	28mm (1.10in)	32mm (1.26in)	40mm (1.57in)	48mm (1.89in)	20mm (0.79in)

7 Maintenance and test instructions

7.1 Stator checking

The following tables show the resistive value between the different connector pins for each stator type. If the value is not within a range of +/- 10% the stator may be damaged (temperature of the stator for all measurements: 20°C).

PS10-70x160U-BD...

...-SSC-QJ (0150-2951)

...-SSC-QJ-D24 (0150-5975)

...-SSC-QJ-D25S (0150-5990)

...-SSC-QJ-D04 (0150-5960)

...-SSC-QJ-D24S (0150-5980)

...-SSC-QJ-D26 (0150-5995)

...-SSC-QJ-D05 (0150-5970)

...-SSC-QJ-D25 (0150-5985)

...-SSC-QJ-D34 (0150-6005)

Phase U / Phase V	Pin 1 / Pin 4	8.3 Ω @ 25 °C
Phase V / Phase W	Pin 4 / Pin 3	8.3 Ω @ 25 °C
Phase W / Phase U	Pin 3 / Pin 1	8.3 Ω @ 25 °C
Casing	Any phases / Casing	> 200 MΩ @ 25 °C
Temp + / Temp - Pt1000 + / Pt1000 - PTC + / PTC -	Pin A / Pin B	200 kΩ @ 25 °C (supply off) 1097 Ω @ 25 °C < 400 Ω @ 25 °C

PS10-70x240U-BD...

...-SSC-QJ (0150-2952)

...-SSC-QJ-D24 (0150-5976)

...-SSC-QJ-D25S (0150-5991)

...-SSC-QJ-D04 (0150-5961)

...-SSC-QJ-D24S (0150-5981)

...-SSC-QJ-D26 (0150-5996)

...-SSC-QJ-D05 (0150-5971)

...-SSC-QJ-D25 (0150-5986)

...-SSC-QJ-D34 (0150-6006)

Phase U / Phase V	Pin 1 / Pin 4	6.3 Ω @ 25 °C
Phase V / Phase W	Pin 4 / Pin 3	6.3 Ω @ 25 °C
Phase W / Phase U	Pin 3 / Pin 1	6.3 Ω @ 25 °C
Casing	Any phases / Casing	> 200 MΩ @ 25 °C
Temp + / Temp - Pt1000 + / Pt1000 - PTC + / PTC -	Pin A / Pin B	200 kΩ @ 25 °C (supply off) 1097 Ω @ 25 °C < 400 Ω @ 25 °C

PS10-70x320U-BD...

...-SSC-QJ (0150-2953)

...-SSC-QJ-D24 (0150-5977)

...-SSC-QJ-D25S (0150-5992)

...-SSC-QJ-D04 (0150-5962)

...-SSC-QJ-D24S (0150-5982)

...-SSC-QJ-D26 (0150-5997)

...-SSC-QJ-D05 (0150-5972)

...-SSC-QJ-D25 (0150-5987)

...-SSC-QJ-D34 (0150-6007)

Phase U / Phase V	Pin 1 / Pin 4	5.5 Ω @ 25 °C
Phase V / Phase W	Pin 4 / Pin 3	5.5 Ω @ 25 °C
Phase W / Phase U	Pin 3 / Pin 1	5.5 Ω @ 25 °C
Casing	Any phases / Casing	> 200 MΩ @ 25 °C
Temp + / Temp - Pt1000 + / Pt1000 - PTC + / PTC -	Pin A / Pin B	200 kΩ @ 25 °C (supply off) 1097 Ω @ 25 °C < 400 Ω @ 25 °C

7.2 Maintenance of linear motors

The person responsible for the operation of the motors must ensure that the specified maintenance work is carried out. The following maintenance schedule is designed for the operating conditions in the food industry with contact of liquid media. The inspection cycle is 2.5 million movement cycles or 1500 friction-kilometer.

7.2.1 Maintenance schedule

When	What	Task
Every 2.5 million movement cycles or 1500 friction-kilometer	Bearing tube Wiper	Check + Possibly replacing the tube and the wipers in case of visible wear. (See section 6.2)
	Slider	Check whether the slider surface is clean and not scratched. Scratched sliders must be replaced, otherwise clean the slider. (See instruction, section 3.2)
	Electrical connection	Tighten the electrical connection between cable and stator. Tightening torque: 0.6 Nm (Q-, J-connector) according to section 5.3 "Connector".
	Fluid cooling (if available)	Check whether the cooling circuit is permanently connected.
	Tightness	<ul style="list-style-type: none"> Check whether the mounting flanges are firmly bolted to the stator without gap. Tightening torque: Cylinder screw M6 (6 Nm)
Ease of movement	If friction is felt during movement, the motor must be stopped immediately. Check the alignment of the load bearing and slider.	

7.2.2 Cleaning

- Pull the sliders carefully out of the stator.
Attention!: Strong magnetic attraction forces (note safety instruction "contusions" on page 5.)! Use non-magnetic material (e.g. wood) to cover close-by iron constructions.
- Clean slider and stator with a soft disposable paper, ideally with the help of LU06 cleaning spray (or acetone or benzene). Available cleaners in the food industry may also be used. However, these should not leave any residues.
- Finally, slider should be inserted according to the chapter 3.2 "Instructions for installing the linear motor".

7.2.3 Cleaning agent

All LinMot stainless steel motors have a protection class of IP69K. Standard cleaning agents in food and pharmaceutical industries with usual concentration and amount, can be used for the cleaning. If necessary, compatibility with the bearing material (Polyamide) and the wiper material (H-ECOPUR) must be checked.

Ordering information

Item	Description	Item-No.
LU06-250	Klüberfood NH1 4-002 Spray* (250 ml)	0150-2394
* LinMot Spray LU06 corresponds to KLÜBERFOOD NH1 4-002 which was developed for the food processing industry.		

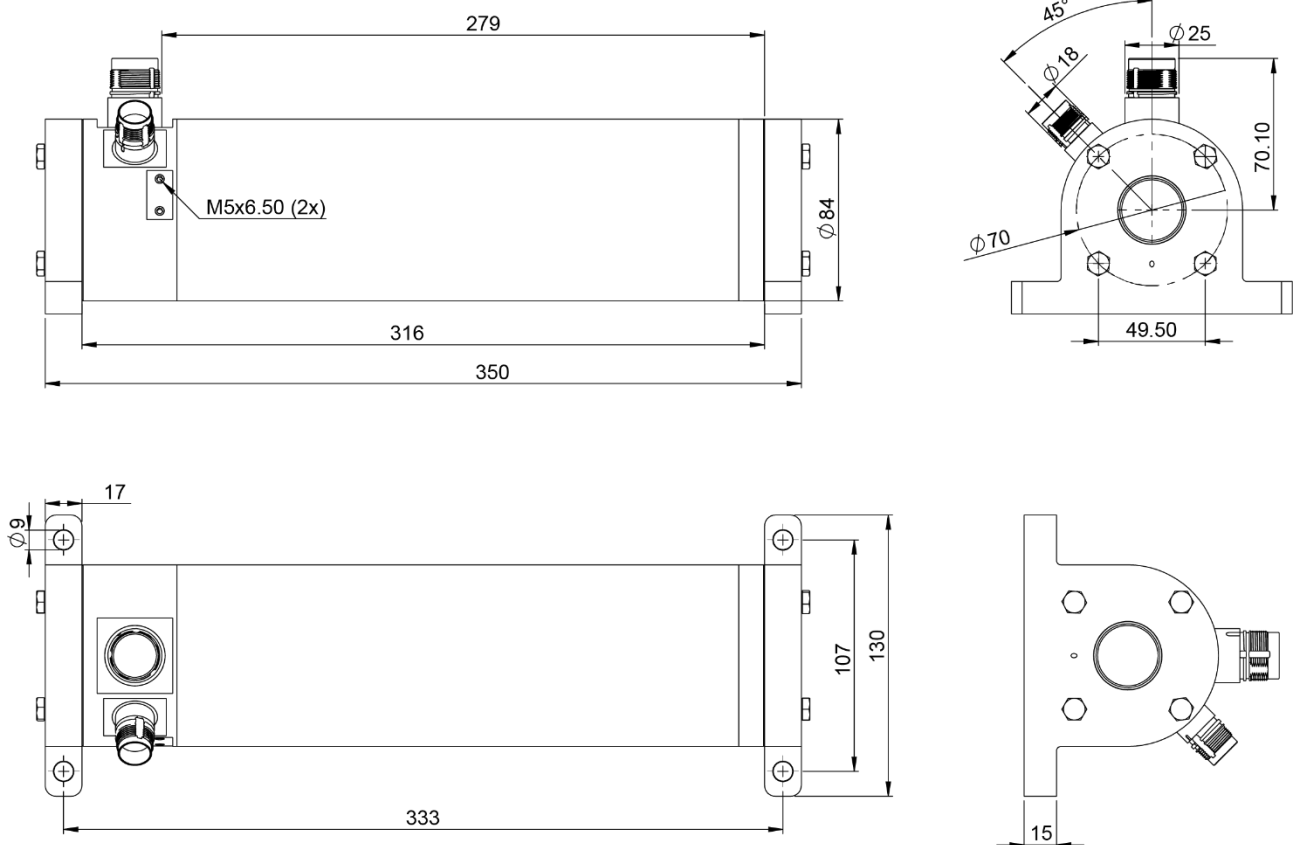
8 Storage, transport, installation altitude

- Sliders are to be stored and transported only in the plastic containers (with cardboard inlay) provided for this purpose, or already installed and secured in LinMot P stators.
- Remove the slider from this plastic containers only for assembling.
- The storage area must be dry, dust-free, frost-free and vibration-free.
- The relative air humidity should be less than 60 %.
- Prescribed storage temperature: -15 °C...70 °C
- The motor must be protected against extreme weather conditions.
- The air in the storage area must not contain any harmful gases.
- The max. installation altitude is 2'000 m (for higher values contact LinMot) above sea level.
Beyond 1'000 m, a derating of 0.5% per 100 m must be taken into account on the rated force in the case of air cooling.

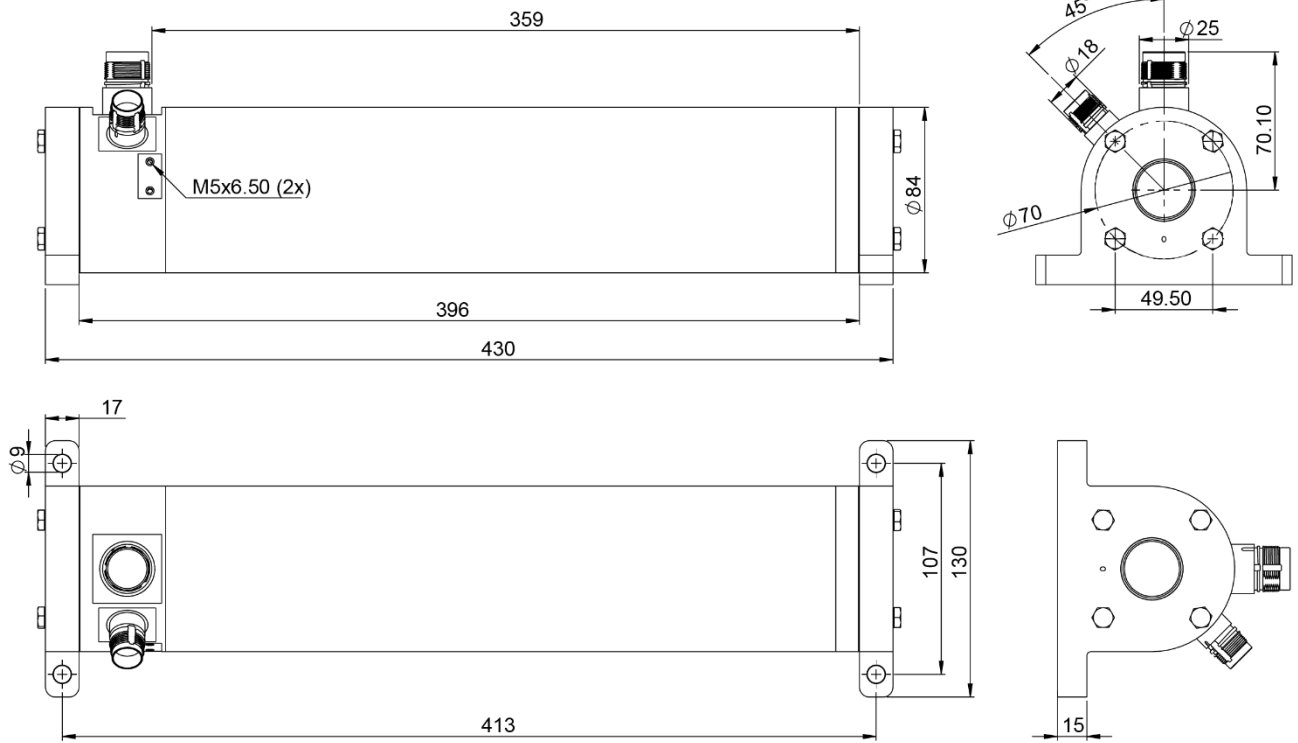
9 Dimensions

9.1 Stator

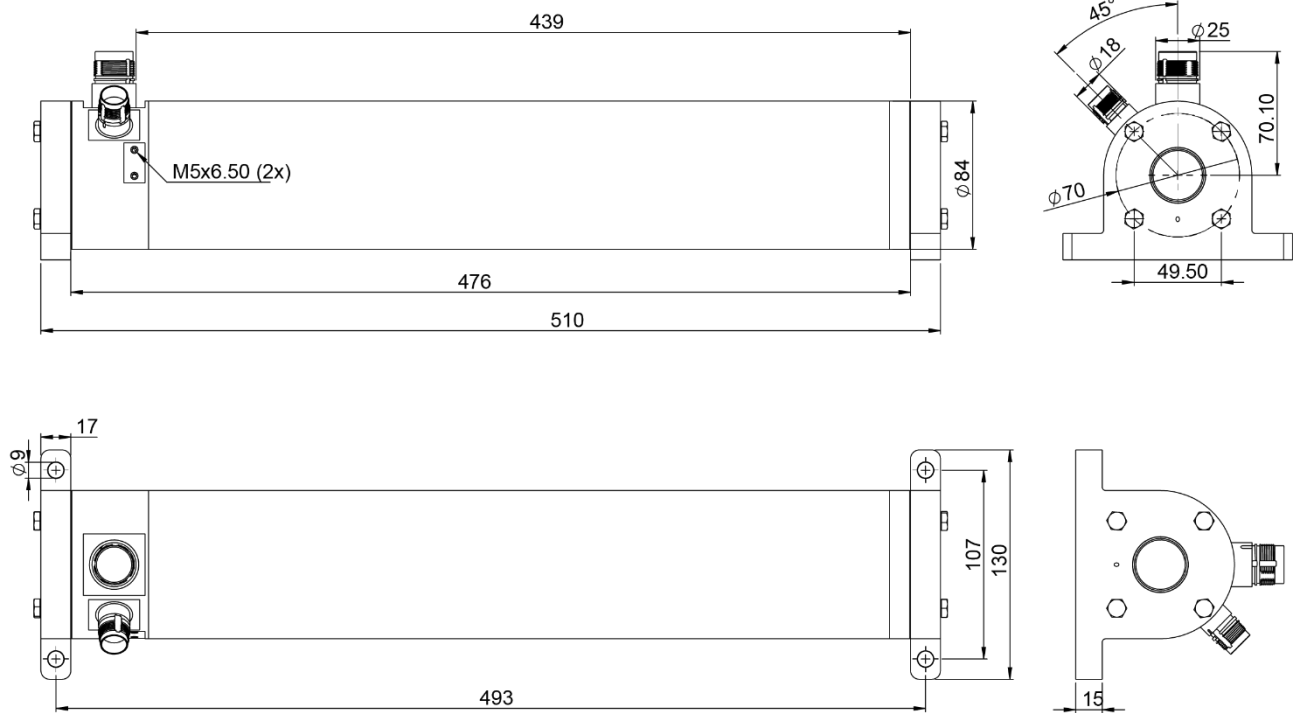
9.1.1 P10-70x160U-BD-SSC



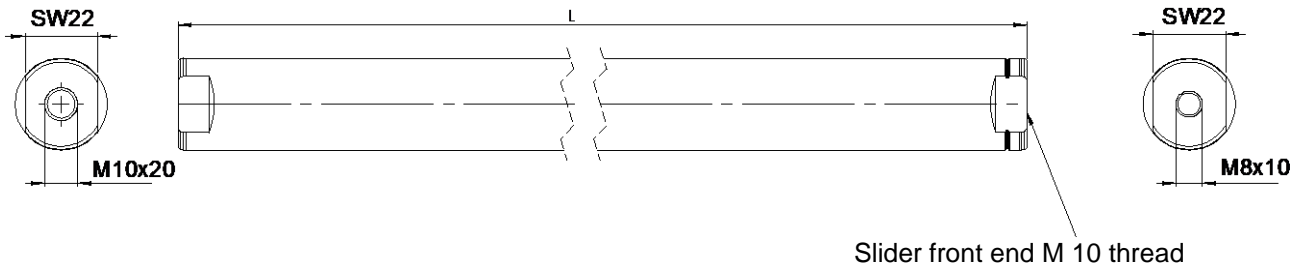
9.1.2 P10-70x240U-BD-SSC



9.1.3 P10-70x320U-BD-SSC






9.2 Slider



Item	Item-No.	Length L [mm / in]
PL10-28x390/340	0150-2194	390 / 15.35
PL10-28x490/440	0150-2195	490 / 19.3
PL10-28x590/540	0150-2196	590 / 23.42
PL10-28x690/640	0150-2197	690 / 27.18
PL10-28x790/740	0150-2198	790 / 31.11
PL10-28x890/840	0150-2199	890 / 35.05
PL10-28x990/940	0150-2203	990 / 39
PL10-28x1190/1140	0150-2204	1190 / 46.87
PL10-28x1390/1340	0150-2205	1390 / 54.75
PL10-28x1590/1540	0150-2206	1590 / 62.62
PL10-28x1790/1740	0150-2207	1790 / 70.5
PL10-28x1990/1940	0150-2208	1990 / 78.38

10 International Certificates

<p>Europe</p> 	<p>See chapter “EU Declaration of Conformity CE-Marking”</p>
<p>UK</p> 	<p>See chapter “UK Declaration of Conformity UKCA-Marking”</p>
<p>IECEE CB SCHEME</p>	<p>Ref. Certif. Nr. CH-8521</p>
<p>USA / Canada</p> 	<p>File Number E354430 Refers to cURus marked motors</p>

	Ref. Certif. No.
	CH-8521



IEC SYSTEM FOR MUTUAL RECOGNITION OF TEST CERTIFICATES FOR ELECTRICAL EQUIPMENT (IECEE) CB SCHEME

CB TEST CERTIFICATE

Product	Linear motor	
Name and address of the applicant	NTI AG	Bodenackerstrasse 2 SWITZERLAND 8957 Spreitenbach
Name and address of the manufacturer	NTI AG	Bodenackerstrasse 2 SWITZERLAND 8957 Spreitenbach
Name and address of the factory	NTI AG	Bodenackerstrasse 2 SWITZERLAND 8957 Spreitenbach
<i>Note: When more than one factory, please report on page 2</i>	<input type="checkbox"/> Additional Information on page 2	
Ratings and principal characteristics	supplied via servo drive, see TR 17-EL-0006.E02 for details	
Trade mark (if any)	LinMot	
Customers's Testing Facility (CTF) Stage used	---	
Model / Type Ref.	PR series PS series P04 series P05 series	
Additional information (if necessary may also be reported on page 2)	---	
A sample of product was tested and found to be in conformity with IEC	<input type="checkbox"/> Additional Information on page 2 IEC 61000-6-2:2016 IEC 61000-6-4:2006, IEC 61000-6-4:2006/AMD1:2010 IEC 61000-6-7:2014	
National differences	EU Group Differences; EU Special National Conditions; EU A-Deviations	
As shown in the Test Report Ref. No. which forms part of this Certificate	17-EL-0006.E01 + .E02 + .Z01	



This CB Test Certificate is issued by the National Certification Body

Electrosuisse Luppenstrasse 1 8320 Fehraltorf SWITZERLAND		
Signed by: Martin Plüss Date: 2017-03-13		page 1 of 1

11 UL Certificate

CERTIFICATE OF COMPLIANCE

Certificate Number UL-US-L354430-11-52105102-2
Report Reference E354430-20150125
Date 5-May-2021

Issued to: NTI AG
 Bodenaeckerstr 2 SPREITENBACH
 Switzerland 8957

**This is to certify that
 representative samples of**

NDMM2 - Incomplete Rotating Machines and Rotating
 Machine Parts - Component

See Addendum Page for Product Designation(s).

Have been investigated by UL in accordance with the
 component requirements in the Standard(s) indicated on
 this Certificate. UL Recognized components are incomplete
 in certain constructional features or restricted in
 performance capabilities and are intended for installation in
 complete equipment submitted for investigation to UL LLC.

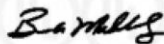
Standard(s) for Safety: UL 1004-1, 2nd Ed., Issue Date: 2012-09-19, Revision
 Date: 2020-11-05

Additional Information: See the UL Online Certifications Directory at
<https://iq.ulprospector.com> for additional information

This *Certificate of Compliance* does not provide authorization to apply the UL Recognized Component Mark.
 Only the UL Follow-Up Services Procedure provides authorization to apply the UL Mark.

Only those products bearing the UL Recognized Component Mark should be considered as being UL Certified
 and covered under UL's Follow-Up Services.

Look for the UL Recognized Component Mark on the product.



Bruce Mahrenholz, Director North American Certification Program

UL LLC

Any information and documentation involving UL Mark services are provided on behalf of UL LLC (UL) or any authorized licensee of UL. For questions, please
 contact a local UL Customer Service Representative at <http://ul.com/about/ullocations>

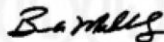


CERTIFICATE OF COMPLIANCE

Certificate Number UL-US-L354430-11-52105102-2
Report Reference E354430-20150125
Date 5-May-2021

This is to certify that representative samples of the product as specified on this certificate were tested according to the current UL requirements

Model	Category Description
P10-70-SSCx160	Incomplete Motor Parts
P10-70-SSCx240	Incomplete Motor Parts
P10-70-SSCx320	Incomplete Motor Parts
P10-70-SSCx400	Incomplete Motor Parts
P10-70-SSCx480	Incomplete Motor Parts
P10-70-SSCx80	Incomplete Motor Parts
P10-70x160+	Incomplete Motor Parts
P10-70x240+	Incomplete Motor Parts
P10-70x320+	Incomplete Motor Parts
P10-70x400+	Incomplete Motor Parts
P10-70x480+	Incomplete Motor Parts
P10-70x80+	Incomplete Motor Parts
PS10-70-SSCx160	Incomplete Motor Parts
PS10-70-SSCx240	Incomplete Motor Parts
PS10-70-SSCx320	Incomplete Motor Parts
PS10-70-SSCx400	Incomplete Motor Parts
PS10-70-SSCx480	Incomplete Motor Parts
PS10-70-SSCx80	Incomplete Motor Parts
PS10-70x160+	Incomplete Motor Parts
PS10-70x240+	Incomplete Motor Parts
PS10-70x320+	Incomplete Motor Parts
PS10-70x400+	Incomplete Motor Parts
PS10-70x480+	Incomplete Motor Parts
PS10-70x80+	Incomplete Motor Parts



Bruce Mahrenholz, Director North American Certification Program

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CERTIFICATE OF COMPLIANCE

Certificate Number UL-CA-L354430-31-52105102-2
Report Reference E354430-20150125
Date 5-May-2021

Issued to: NTI AG
Bodenaeckerstr 2 SPREITENBACH
Switzerland 8957

This is to certify that representative samples of NDMM8 - Incomplete Rotating Machines and Rotating Machine Parts Certified for Canada - Component
See Addendum Page for Product Designation(s).

Have been investigated by UL in accordance with the component requirements in the Standard(s) indicated on this Certificate. UL Recognized components are incomplete in certain constructional features or restricted in performance capabilities and are intended for installation in complete equipment submitted for investigation to UL LLC.

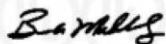
Standard(s) for Safety: CSA C22.2 NO. 100, 7th Ed., Issue Date: 2014-07-01, Revision Date: 2017-04-01

Additional Information: See the UL Online Certifications Directory at <https://iq.ulprospector.com> for additional information

This *Certificate of Compliance* does not provide authorization to apply the UL Recognized Component Mark. Only the UL Follow-Up Services Procedure provides authorization to apply the UL Mark.

Only those products bearing the UL Recognized Component Mark should be considered as being UL Certified and covered under UL's Follow-Up Services.

Look for the UL Recognized Component Mark on the product.



Bruce Mahrenholz, Director North American Certification Program

UL LLC

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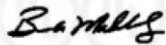


CERTIFICATE OF COMPLIANCE

Certificate Number UL-CA-L354430-31-52105102-2
Report Reference E354430-20150125
Date 5-May-2021

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P10-70x240+	Incomplete Motor Parts
P10-70x320+	Incomplete Motor Parts
P10-70x400+	Incomplete Motor Parts
P10-70x480+	Incomplete Motor Parts
P10-70x80+	Incomplete Motor Parts
PS10-70-SSCx160	Incomplete Motor Parts
PS10-70-SSCx240	Incomplete Motor Parts
PS10-70-SSCx320	Incomplete Motor Parts
PS10-70-SSCx400	Incomplete Motor Parts
PS10-70-SSCx480	Incomplete Motor Parts
PS10-70-SSCx80	Incomplete Motor Parts
PS10-70x160+	Incomplete Motor Parts
PS10-70x240+	Incomplete Motor Parts
PS10-70x320+	Incomplete Motor Parts
PS10-70x400+	Incomplete Motor Parts
PS10-70x480+	Incomplete Motor Parts
PS10-70x80+	Incomplete Motor Parts



Bruce Mahrenholz, Director North American Certification Program

UL LLC

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12 EU Declaration of Conformity CE-Marking

NTI AG / LinMot®
Bodenaeckerstrasse 2
8957 Spreitenbach

Switzerland

Tel.: +41 (0)56 419 91 91

Fax: +41 (0)56 419 91 92

declares under sole responsibility the compliance of the products:

- Linear Motors of the Series **PS10-70xxx-xx-xx**
- Linear Motors of the Series **PS10-70xxx-xx-xx-D04**
- Linear Motors of the Series **PS10-70xxx-xx-xx-D05**
- Linear Motors of the Series **PS10-70xxx-xx-xx-D24**
- Linear Motors of the Series **PS10-70xxx-xx-xx-D24S**
- Linear Motors of the Series **PS10-70xxx-xx-xx-D25**
- Linear Motors of the Series **PS10-70xxx-xx-xx-D25S**
- Linear Motors of the Series **PS10-70xxx-xx-xx-D26**
- Linear Motors of the Series **PS10-70xxx-xx-xx-D34**

with the Low Voltage Directive 2014/35/EU 2014/35/EU.

Applied harmonized standards:

- **EN 61800-5-1: 2007**

with the EMC Directive 2014/30/EU.

Applied harmonized standards:

- **EN 61000-6-2: 2005 (Immunity for industrial environments)**
- **EN 61000-6-4: 2007 (Emission for industrial environments)**

According to the EMC directive, the listed devices are not independently operable products.

Compliance of the directive requires the correct installation of the product, the observance of specific installation guides and product documentation. This was tested on specific system configurations.

The safety instructions of the manuals are to be considered.

The product must be mounted and used in strict accordance with the installation instructions contained within the installation guide, a copy of which may be obtained from NTI AG.

Company: NTI AG
Spreitenbach, 25.08.2023



Dr.-Ing. Ronald Rohner
CEO NTI AG

13 UK Declaration of Conformity UKCA-Marking

NTI AG / LinMot®
Bodenaeckerstrasse 2
8957 Spreitenbach

Switzerland

Tel.: +41 (0)56 419 91 91

Fax: +41 (0)56 419 91 92

declares under sole responsibility the compliance of the products:

- Linear Motors of the Series **PS10-70xxx-xx-xx**
- Linear Motors of the Series **PS10-70xxx-xx-xx-D04**
- Linear Motors of the Series **PS10-70xxx-xx-xx-D05**
- Linear Motors of the Series **PS10-70xxx-xx-xx-D24**
- Linear Motors of the Series **PS10-70xxx-xx-xx-D24S**
- Linear Motors of the Series **PS10-70xxx-xx-xx-D25**
- Linear Motors of the Series **PS10-70xxx-xx-xx-D25S**
- Linear Motors of the Series **PS10-70xxx-xx-xx-D26**
- Linear Motors of the Series **PS10-70xxx-xx-xx-D34**

with the Electrical Equipment (Safety) Regulations 2016 SI 2016 No. 1101

Applied designated standards:

- **EN 61800-5-1: 2007**

with the EMC Regulation S.I. 2016 No. 1091.

Applied designated standards:

- **EN 61000-6-2: 2005 (Immunity for industrial environments)**
- **EN 61000-6-4: 2007 (Emission for industrial environments)**

According to the EMC regulation, the listed devices are not independently operable products.

Compliance of the regulation requires the correct installation of the product, the observance of specific installation guides and product documentation. This was tested on specific system configurations.

The safety instructions of the manuals are to be considered.

The product must be mounted and used in strict accordance with the installation instructions contained within the installation guide, a copy of which may be obtained from NTI AG.

Company: NTI AG
Spreitenbach, 25.08.2023



Dr.-Ing. Ronald Rohner
CEO NTI AG

ALL LINEAR MOTION FROM A SINGLE SOURCE

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NTI AG - LinMot & MagSpring

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CH-8957 Spreitenbach

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support@linmot.com

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LinMot USA, Inc.

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Web: <http://www.linmot-usa.com/>

Visit <http://www.linmot.com/> to find a distributor next to you.